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# From Jacobian to Hessian: distributional form and relaxation (\*\*)

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### 1 - Introduction

Recently higher order variational problems have attracted a great deal of attention due in part to their relevance in the study of problems emerging from materials science and engineering, including the Blake-Zisserman model for image segmentation in computer vision, singular perturbation approaches for phase

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transitions in elastic materials, the treatment of ferromagnetic and micromagnetic materials, and thin structure models leading to membrane, shell, and plate theories (e.g., see Conti, Fonseca & Leoni [21], Choksi, Kohn & Otto [18], Carriero, Leaci & Tomarelli [17], DeSimone [25], Kohn & Müller [45], Müller [52], Owen & Paroni [58], Rivière & Serfaty [60]).

Several attempts have been made to reduce these problems to the first order setting, where nowadays there is a considerable mastery of techniques within the realm of the Calculus of Variations. Here we highlight the work in Dal Maso, Fonseca, Leoni & Morini [24] (see also a preceding work by Müller & Šverák [56]) where it is proved that, up to mild regularity conditions, a higher order quasiconvex function with superlinear growth is simply the restriction of a (one-)quasiconvex function to the appropriate linear subspace of matrices. The linear growth case remains open as the techniques used in [24] do not apply. Indeed, it is now clear that first order techniques often cannot be naturally extended to tackle certain higher order problems, and the analytical and geometrical constraints that higher order derivatives are endowed require new theoretical arguments, as it will be illustrated below.

In this paper we pursue this avenue of thought now directed to Jacobians of higher order. Here we will draw a parallel between the theory developed for the distributional generalization of the notion of determinant of a gradient,  $\mathcal{J}u$ , to the determinant of the matrix of second order derivatives,  $\mathcal{H}u$ . The need to search for the least integrability spaces where  $\mathcal{J}u$  is well defined and where weak continuity and mild regularity properties still hold, is motivated in part by issues in nonlinear elasticity and vorticity effects in Ginzburg-Landau type models (e.g. see Alberti, Balso & Orlandi [3], Ball [8], Bethuel, Brézis & Heléin [11], Fonseca, Leoni, Malý & Paroni [31], James & Spector [42], Jerrard & Soner [44], Müller & Spector [55]). A considerable progress in this regard has been achieved merging ideas from partial differential equations, continuum mechanics, the calculus of variations and geometric measure theory (e.g. see Ball [7], Brézis, Fusco & Sbordone [13], Brézis & Nirenberg [14], [15], Coifman, Lions, Meyer & Semmes [19], Dacorogna & Murat [23], Fonseca, Fusco & Marcellini [27], [28], Fonseca, Leoni & Malý [30], Giaquinta, Modica & Souček [35], [36], Hajlasz [38], Iwaniec & Sbordone [41], Müller [51], [52], [53], Müller, Tang & Yan [54]). It all starts with the observation that (see Morrey [49] and Reshetnyak [59])

$$u_n \rightharpoonup u \text{ in } W^{1,N}(\Omega;\mathbb{R}^N) \Rightarrow \det \nabla u_n \stackrel{*}{\rightharpoonup} \det \nabla u \text{ in the sense of measures},$$

where  $\Omega$  is a bounded domain in  $\mathbb{R}^{\mathbb{N}}$ . This is consequence of a simple integration by parts and of the fact that if  $u \in W^{1,N}(\Omega;\mathbb{R}^N)$  then the Jacobian determinant

 $\det \nabla u$  agrees with the distribution

$$\mathcal{J}_1 u = \operatorname{Det} \nabla u := \sum_{i=1}^N (-1)^{i+1} \frac{\partial}{\partial x_i} \left( u_1 \frac{\partial (u_2, \dots, u_N)}{\partial (x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_N)} \right),\,$$

i.e.

(1) 
$$\langle \operatorname{Det} u, \phi \rangle = -\int_{\Omega} u_1 \det(\nabla \phi, \nabla u_2, \dots, \nabla u_N) dx$$

for  $\phi \in C_{\mathrm{c}}^{\infty}(\Omega)$ . The treatment of such a distributional form of Jacobian was initiated by Ball [7]. The spaces  $W^{1,N^2/(N+1)}(\Omega;\mathbb{R}^N)$  and  $W^{1,N-1}(\Omega;\mathbb{R}^N) \cap L^{\infty}(\Omega;\mathbb{R}^N)$  are commonly adopted as domains of definition of the operator  $\mathcal{J}_1$ .

We want to discuss and compare various choices of domains and weak forms of J, the classical pointwise Jacobian operator, well defined on  $W^{1,N}(\Omega;\mathbb{R}^N)$ . This leads us to the following general definition.

Definition 1.1. A topological or convergence space  $\mathcal{X}$  of measurable functions  $u: \Omega \to \mathbb{R}^N$  is said to be an *admissible domain for the weak Jacobian*  $\mathcal{J}$  if

- (i)  $C^1(\Omega; \mathbb{R}^{\mathbb{N}}) \cap \mathcal{X}$  is dense in  $\mathcal{X}$ :
- (ii) the mapping  $J: u \mapsto \det \nabla u$  from  $C^1(\Omega; \mathbb{R}^N) \cap \mathcal{X}$  to  $\mathcal{D}'$  has a unique continuous extension  $\mathcal{J}: \mathcal{X} \to \mathcal{D}'$ .

Here the framework of «convergence space» stands for a set X endowed with a notion of sequential convergence (e.g. strong convergence, weak convergence, weak\* convergence or BV-strict convergence).

It turns out that  $W^{1,N-1}(\Omega;\mathbb{R}^N)\cap L^\infty(\Omega;\mathbb{R}^N)$ ) is an admissible domain with the weak convergence on  $W^{1,N-1}(\Omega;\mathbb{R}^N)$  and the strong convergence on  $L^\infty(\Omega;\mathbb{R}^N)$ . Another admissible domain is  $W^{1,p}(\Omega;\mathbb{R}^N)$  for  $p>N^2/(N+1)$  endowed with the weak convergence, and, more generally, we may consider  $W^{1,p}(\Omega,\mathbb{R}^N)\cap L^s(\Omega,\mathbb{R}^N)$  with

$$\frac{N-1}{p} + \frac{1}{s} \le 1,$$

equipped with the weak convergence on  $W^{1,p}(\Omega,\mathbb{R}^N)$  and the strong convergence on  $L^s(\Omega,\mathbb{R}^N)$ . In all these cases it is easy to see that Hölder inequality (and Sobolev Embedding Theorem in the case  $p \geq N^2/(N+1)$ ) ensures that the products involved in the definition of  $\mathrm{Det}\nabla u$  are well defined in  $L^1$ , and for  $p > N^2/(N+1)$  Rellich-Kondrachov Compactness Theorem yields strong convergence in  $L^s$  with s the conjugate exponent of  $\frac{p}{N-1}$ . Thus (1) is the formula for the weak Jacobian  $\mathcal J$  in

these spaces. For this approach to weak Jacobians see e.g. Ball [7], Ball & Murat [10], Ball, Currie & Olver [9], Dacorogna & Murat [23], Fonseca, Leoni & Malý [30], Olver [57].

Not all notions of weak Jacobian involve integration by parts. Alberti & Ambrosio [2] proved that  $C^1 \cap \mathcal{M}on(\Omega)$  is an admissible domain for the weak Jacobian, where  $\mathcal{M}on(\Omega)$  is the class of functions in  $\Omega$  which agree almost everywhere with some (maximal) monotone function  $\overline{u}$  whose domain includes  $\Omega$ , and here it takes the form

$$\mathcal{J}(u)(B) = |\overline{u}(B)|$$

for every Borel set  $B \subset\subset \Omega$ .

But we must move beyond first order determinants. Indeed, several geometric problems involving Gaussian curvatures and issues in the theory of nonlinear partial differential equations ranging from the equations of gas dynamics for subsonic flows to minimal surfaces or the p-harmonic equation  $\operatorname{div}(|\nabla u|^{p-2}\nabla u)=0$ , call for the mastery of weak forms of the Hessian.

In this paper we search for a weak form,  $\mathcal{H}u$ , of the Hessian of a map  $u:\Omega\to\mathbb{R}$  where  $\Omega$  is bounded open set in  $\mathbb{R}^N$ , that will allow us to draw a parallel with the study of the weak Jacobian  $\mathcal{J}$ , and to make some progress toward answering the following questions:

- when can we ensure that  $u_n \to u$  implies  $\mathcal{H}u_n \to \mathcal{H}u$  in the sense of distributions, for an appropriate notion of weak convergence?
- when can we recover  $\det \nabla^2 u$  as an «absolutely continuous part» of  $\mathcal{H}u$  (see Müller [51]) for the Jacobian)?
  - can we characterize the relaxed energy

$$\mathcal{F}(u,U) := \inf_{\{u_n\}} \left\{ \liminf_{n o +\infty} \int\limits_{\Omega} \left| \det 
abla^2 u_n(x) 
ight| dx : u_n \in C^{\infty}(\Omega), u_n 
ightharpoonup u 
ight\}$$

for an appropriate notion of weak convergence (see Fonseca, Fusco & Marcellini [27], [28], for the Jacobian)?

There are many different ways to define a distributional Hessian, and their significance and properties depend greatly on the choice of domain. Among all these forms one stands out as capturing the good properties that we have come to expect by analogy with the study of  $\text{Det}\nabla u$ . To illustrate this, and following Iwaniec [39], we consider the two dimensional case where  $u:\Omega\to\mathbb{R}$ ,  $\Omega$  is an open bounded subset of  $\mathbb{R}^2$ , and we arrive at four distributional notions of the Hessian:

– zero order Hessian 
$$\mathcal{H}_0:W^{2,2}_{\mathrm{loc}}(\Omega) o L^1_{\mathrm{loc}}(\Omega)\subset \mathcal{D}_0'(\Omega),$$
  $\mathcal{H}_0(u):=u_{xx}u_{yy}-u_{xy}^2,$ 

– first order Hessian  $\mathcal{H}_1:W^{2,4/3}_{\mathrm{loc}}(\Omega) o L^1_{\mathrm{loc}}(\Omega)\subset \mathcal{D}_1'(\Omega),$ 

$$\mathcal{H}_1(u) := (u_x u_{yy})_x - (u_x u_{xy})_y (u_y u_{xx})_y - (u_y u_{xy})_x,$$

- second order Hessian  $\mathcal{H}_2:W^{2,1}_{\mathrm{loc}}(\Omega)\to\mathcal{D}_2'(\Omega),$ 

$$\mathcal{H}_2(u) := \frac{1}{2} [(uu_{xx})_{yy} + (uu_{yy})_{xx} - (uu_{xy})_{xy}],$$

- very weak Hessian  $\mathcal{H}_2^*: W^{1,2}_{loc}(\Omega) \to \mathcal{D}_2'(\Omega),$ 

$$\mathcal{H}_{2}^{*}(u) := (u_{x}u_{y})_{xy} - \frac{1}{2}(u_{x}u_{x})_{yy} - \frac{1}{2}(u_{y}u_{y})_{xx},$$

where  $\mathcal{D}_0'(\Omega)$  stands for the space of distributions in  $\Omega$  of order  $k, k = 0, 1, \ldots$ 

Clearly, any two of these functionals coincide in the intersection of their domains. Here we focus on  $\mathcal{H}_2^*(u)$  as it is the weakest formulation among all four above.

In the three dimensional case, the very weak Hessian  $\mathcal{H}_2^*:W^{2,9/5}_{\mathrm{loc}}(\Omega)\to\mathcal{D}_2'(\Omega)$  is defined by

$$\mathcal{H}_{2}^{*}u = \frac{1}{6} [(2u_{y}u_{z}u_{yz} - u_{y}^{2}u_{zz} - u_{z}^{2}u_{yy})_{xx}$$

$$+ (2u_{z}u_{x}u_{xz} - u_{z}^{2}u_{xx} - u_{x}^{2}u_{zz})_{yy}$$

$$+ (2u_{x}u_{y}u_{xy} - u_{x}^{2}u_{yy} - u_{y}^{2}u_{xx})_{zz}$$

$$+ 2(u_{x}u_{y}u_{zz} + u_{z}^{2}u_{xy} - u_{x}u_{z}u_{yz} - u_{z}u_{y}u_{zx})_{xy}$$

$$+ 2(u_{y}u_{z}u_{xx} + u_{x}^{2}u_{yz} - u_{x}u_{z}u_{xy} - u_{x}u_{y}u_{zx})_{yz}$$

$$+ 2(u_{z}u_{x}u_{yy} + u_{y}^{2}u_{xz} - u_{y}u_{x}u_{yz} - u_{y}u_{z}u_{xy})_{yz}].$$

It can be shown that, in contrast with the two dimensional case, it is not possible to find a clever way of using integration by parts that will lead to a formula involving no derivatives of order two.

All the forms of weak Hessian considered above in dimension two have their counterparts in higher dimension (we follow Iwaniec [39], see also Ball, Currie & Olver [9], Dacorogna & Murat [23], Olver [57], among others). The operator  $\mathcal{H}_0$  assigns to  $u \in W_{\text{loc}}^{2,N}$  the pointwise Hessian Hu. The operator  $\mathcal{H}_1$  is the weak Jacobian applied to the gradient, namely,  $\mathcal{H}_1 u = \text{Det}\nabla(\nabla u)$ ,  $u \in W_{\text{loc}}^{2,N^2/(N+1)}$ . In the space  $W_{\text{loc}}^{2,N-1}$  the operator  $\mathcal{H}$  takes the form

$$\langle \mathcal{H}_2 u, \phi \rangle = \frac{1}{N} \sum_{i=1}^N \int_{\Omega} u \det(\nabla D_1 u, \dots, \nabla D_{i-1} u, \nabla D_i \phi, \nabla D_{i+1} u, \nabla D_N u) dx.$$

The very weak distributional form of the Hessian is  $\mathcal{H}_2^*u:W^{2,N^2/(N+2)}_{\mathrm{loc}}(\Omega) o \mathcal{D}_2'(\Omega)$ 

given by

$$\langle \mathcal{H}_{2}^{*}u, \phi \rangle = -\frac{1}{N!} \sum_{p,q \in P} \operatorname{sgn} p \operatorname{sgn} q \int_{\Omega} D_{p_{1}} u D_{q_{1}} u D_{p_{2}q_{2}} \phi D_{p_{3}q_{3}} u \dots \mathcal{D}_{p_{N}q_{N}} u \, dx$$

$$= -\frac{1}{N!} \sum_{p \in P} \operatorname{sgn} p \int_{\Omega} \det(D_{p_{1}} u \nabla u, \nabla D_{p_{2}} \phi, \nabla D_{p_{3}} u, \dots, \nabla D_{p_{N}} u) \, dx,$$

where P be the set of all permutations of  $\{1,\ldots,N\}$  and  $\phi\in C_{\mathrm{c}}^{\infty}(\Omega)$ .

As in the case of weak Jacobians, there are several choices of domains for weak forms of H, the pointwise Hessian operator  $u \mapsto \det \nabla^2 u$ , and we are led to the following definition.

Definition 1.2. A topological or convergence space  $\mathcal{X}$  of measurable functions  $u: \Omega \to \mathbb{R}$  is said to be an *admissible domain for the weak Hessian*  $\mathcal{H}$  if

- (i)  $C^2(\Omega) \cap \mathcal{X}$  is dense in  $\mathcal{X}$ ;
- (ii) the mapping  $H: u \mapsto \det \nabla^2 u$  from  $C^2(\Omega) \cap \mathcal{X}$  to  $\mathcal{D}'$  has a unique continuous extension  $\mathcal{H}: \mathcal{X} \to \mathcal{D}'$ .

We start by showing that

Theorem 1.3. If N=2 then  $W^{1,2}(\Omega)$  endowed with the strong convergence is an admissible domain for the weak Hessian, and the extension of H to  $W^{1,2}(\Omega)$  is the operator  $\mathcal{H}_2^*$ .

If  $N \geq 3$  then  $W^{2,p}(\Omega) \cap W^{1,s}(\Omega)$ , with the weak convergence on  $W^{2,p}(\Omega)$  and the strong convergence on  $W^{1,s}(\Omega)$ , and with

$$\frac{N-2}{p} + \frac{2}{s} \le 1,$$

is an admissible domain for the weak Hessian. Precisely, if  $u_n \in W^{2,N}(\Omega)$  are such that  $u_n \to u$  in  $W^{1,s}(\Omega)$  and  $u_n \to u$  in  $W^{2,p}(\Omega)$  then

$$\det \nabla^2(u_n) \to \mathcal{H}u \quad \text{in } \mathcal{D}'.$$

Furthermore, Hu acts on test functions as in (3).

We remark that, in view of Sobolev's Embedding Theorem, (4) is satisfied if  $p=\frac{N^2}{N+2}$ ,  $s=p^*$ , and here  $\mathcal{H}u$  is well defined as a distribution of order 2. Moreover, if  $u_n \rightharpoonup u$  in  $W^{2,p}$  with  $p>\frac{N^2}{N+2}$ , then by Rellich-Kondrachov Compactness Theorem we are in position to apply this theorem with  $s:=2\left(\frac{p}{N-2}\right)'$ , where in

general r' stands for the conjugate exponent of r. This result was previously obtained by Dacorogna & Murat [23]. They also showed that  $W^{N^2/(N+2)}$  is not an admissible domain when equipped with the weak convergence «only». Also, Iwaniec [39] proved that for N=2 the functional  $\mathcal{H}_2^*$  is not weakly continuous, precisely there exists a sequence  $\{u_n\}$  converging weakly to zero in  $W^{1,2}(\Omega)$  (even in  $W^{1,p}(\Omega)$ ) weak with p>2, so this phenomenon is not a «borderline»-type result) such that  $H_2^*(u_n)$  does not go to zero in  $\mathcal{D}'(\Omega)$ , i.e.  $W^{1,2}(\Omega)$  with the weak convergence is not an admissible domain for the weak Hessian.

Jerrard & Jung [43] showed that  $BV^2(\Omega) \cap W^{1,\infty}(\Omega)$  with the strict convergence on  $BV^2$  and weak\* convergence on  $W^{1,\infty}$  is an admissible domain for the weak Hessian, where  $BV^2(\Omega) := \{u \in W^{1,1}(\Omega) : \nabla u \in BV(\Omega; \mathbb{R}^N)\}.$ 

Clearly, if  $u \in W^{2,p}_{\mathrm{loc}}(\Omega)$  with  $p \geq \frac{N^2}{N+1}$ , then  $\mathcal{H}u = \mathrm{Det}\,\nabla(\nabla u)$ . In Theorem 1.3 it was important to exploit the structure of second order derivatives. Had we looked only at  $\mathrm{Det}\,\nabla(\nabla u)$  we would have needed  $W^{2,\frac{N^2}{N+1}}(\Omega)$  in order to draw a similar conclusion.

In connection with the Monge-Ampère equation, several authors have introduced measure-valued Hessian operators on the family of convex functions equipped mostly with the topology of locally uniform convergence, see e.g. Alexandrov [4], Bakelman [6], Trudinger & Wang [61], Alberti & Ambrosio [2] and references therein. In fact, the weak Hessian of a convex function is the weak Jacobian of its subgradient in the sense of [2].

Next we compare  $\mathcal{H}(u)$  with the pointwise Hessian. We will regularize the weak Hessian by a standard family  $\{\psi_{\varepsilon}\}_{\varepsilon>0}$  of mollifiers, i.e.  $\psi_{\varepsilon}$  are nonnegative functions from  $C_c^{\infty}(\mathbb{R}^N)$  with support in  $\overline{B}(0,\varepsilon)$  such that  $\int \psi_{\varepsilon} dx = 1$ , and they obey the scaling rule

(5) 
$$\psi_{\varepsilon}(x) = \varepsilon^{-N} \psi_{1}(x/\varepsilon), \qquad x \in \mathbb{R}^{N}, \ \varepsilon > 0.$$

Theorem 1.4. Let N=2 and  $u\in W^{1,2}(\Omega)\cap BV^2(\Omega)$ , or let  $N\geq 3$  and  $u\in W^{2,p}(\Omega)$  with  $p\geq \frac{N^2}{N+2}$ . Let  $\{\psi_\varepsilon\}_{\varepsilon>0}$  be a standard family of mollifiers. Then for a.e.  $x\in\Omega$ ,  $(\mathcal{H}u*\psi_\varepsilon)(x)\to\det\nabla^2 u(x)$ , where  $\nabla^2 u$  stands for the absolutely continuous part of  $D^2u$  with respect to the 2-dimensional Lebesgue measure when N=2. In particular, if  $\mathcal{H}u$  is a Radon measure then its absolutely continuous part with respect to the N-dimensional Lebesgue measure is  $\det\nabla^2 u$ .

Iwaniec [39] established this result for  $u \in W^{2,N-1}(\Omega)$ ; note that  $W^{2,N-1}(\Omega) \subset W^{2,\frac{N^2}{N+2}}(\Omega)$ . For the case of the Jacobian, we refer to Müller [51] (see also Iwaniec &

Martin [40], Iwaniec and Sbordone [41], Greco [37], Müller, Qi and Yan [54], Fonseca and Leoni [29] for other so called det = Det results).

It is interesting here to call the attention to the fact that different admissible domains do carry different properties. We know from Müller [51] that the analog of Theorem 1.4 holds for  $\operatorname{Det} \nabla u$  provided  $p \geq \frac{N^2}{N+1}$ . This is false in the admissible space  $W^{1,N-1}(\Omega;\mathbb{R}^N) \cap \mathbb{L}^\infty(\Omega;\mathbb{R}^N)$ . We observe that if the admissibility of the space is based on the duality pairing between adj  $\nabla u \in L^{p/(N-1)}$  and  $u \in L^s$  and  $W^{1,p}$  is not embedded to  $L^s$  (such is the case of  $W^{1,N-1} \cap L^\infty$ ), then the weak Jacobian loses a part of its stability. Precisely,

Theorem 1.5. Let  $N-1 \le p < N^2/(N+1)$ . Then there exist a bounded function  $u \in W^{1,p}(Q(0,1),\mathbb{R}^N)$ , a standard family  $\{\psi_{\varepsilon}\}$  of mollifiers, and a set  $E \subset \mathbb{R}^N$  of positive measure such that u = 0 on E, with

$$\lim\sup_{\varepsilon\to 0+} (\mathrm{Det}\nabla u * \psi_{\varepsilon})(x) > 0, \qquad x \in E.$$

Similarly to Theorem 1.5, we can prove

Theorem 1.6. Let  $N-2 \le p < N^2/(N+2)$ . Then there exist a Lipschitz function  $u \in W^{2,p}(Q(0,1),\mathbb{R}^N)$ , a standard family  $\{\psi_{\varepsilon}\}$  of mollifiers, and a set  $E \subset \mathbb{R}^N$  of positive measure such that u=0 on E, with

$$\limsup_{\varepsilon \to 0+} (\mathcal{H}u * \psi_{\varepsilon})(x) > 0, \qquad x \in E.$$

Theorems 1.5 and 1.6 will be proved in a subsequent paper [33].

At this point, we may ask what can we say about the dimensionality of the singular part of  $\mathcal{H}u$  when this is a Radon measure. Müller in [53] proved that if  $a \in (0, N)$  then there exists  $u \in W^{1,p}(\Omega; \mathbb{R}^N) \cap \mathbb{C}(\overline{\Omega}; \mathbb{R}^N)$  for all  $1 \leq p < N$  such that

$$\operatorname{Det} \nabla u = \det \nabla u \mathcal{L}^N \lfloor \Omega + \mu_s$$

where  $\mu_s$  is a positive Radon measure, singular with respect to  $\mathcal{L}^N$  and such that supp  $\mu_s$  is a closed set of Hausdorff dimension a. The a-dimensionality of  $\mu_s$  is supported by the fact that  $\mu_s$  is absolutely continuous with respect to  $\mathcal{H}^a$ . The Hessian counterpart of this existence result is also true, and it was established by Alberti & Ambrosio [2].

Next, we move on to relaxation results for the weak Hessian. We first extend to the k-th order context the relaxation results obtained for first order problems (see Fonseca & Malý [32], Bouchitté, Fonseca & Malý [12]; see also Marcellini [48],

Fonseca & Marcellini [34]). Precisely, let

(6) 
$$F(u, U) = \int_{U} f(\nabla^{k} u) dx$$

where U is an open subset of the open bounded set  $\Omega \subset \mathbb{R}^N$ ,  $f: E_k^{N \times d} \to \mathbb{R}$  is a continuous function and  $E_k^{N \times d}$  denotes the space of all symmetric k-linear maps from  $\mathbb{R}^N$  to  $\mathbb{R}^d$ . Consider

$$\mathcal{F}(u,U,(W^{k,p},w)):=\inf_{\{u_n\}}\Bigl\{\liminf_n F(u_n,U): u_n\in\mathcal{C}^\infty(U),\quad u_n\rightharpoonup u\ \ \text{in}\ \ W^{k,p}(U)\Bigr\}.$$

The following theorem has been proven in the particular case where  $k \geq 2$  and  $q < \frac{Nk-N}{Nk-N-1} \, p$  by Esposito & Mingione [26]. We note  $\frac{N}{N-1} > \frac{Nk-N}{Nk-N-1}$  if k > 2.

Theorem 1.7. Let F satisfy

$$\gamma |\xi|^p \le f(\xi) \le C(1+|\xi|^q).$$

with

(8) 
$$1$$

If  $u \in W^{k,p}(\Omega, \mathbb{R}^d)$  and  $\mathcal{F}(u, \Omega, (W^{k,p}, w)) < \infty$  then there exists a Radon measure  $\mathcal{R}(u, \cdot)$  on  $\Omega$  such that

$$\mathcal{R}(u, U) = \mathcal{F}(u, U, (W^{k,p}, w))$$

for every open set  $U \subset \Omega$ . Moreover, the absolutely continuous part of  $\mathcal{R}(u,\cdot)$  is  $Q_k f(\nabla^k u)$ .

We recall that by  $Q_k f$  we denote the k-quasiconvex envelope of f, namely

$$Q_k f(\xi) = \inf \left\{ \int_B f(\xi + \nabla^k \varphi) \, dx, \ \varphi \in C_c^{\infty}(B) \right\},$$

here *B* is the unit ball in  $\mathbb{R}^N$ .

The method of Bouchitté, Fonseca & Malý [12] is based on extension and trace preserving operators. Here we modify the method to avoid the use of extension operators and the argument is now based on trace preserving operators. Not only this renders it more transparent, even in the case where k=1 thus simplifying earlier work in [12], but also for higher order problems the advantage is notable. In particular, we do not need to differentiate boundary traces when dealing with  $k \geq 2$ !

With this in hand, we take d = 1, q = N, k = 2, set

$$F(u, U) := \int_{U} |\det \nabla^2 u| \, dx,$$

and denote the corresponding relaxation and relaxation measure by  $\mathcal{F}_H$ ,  $\mathcal{R}_H$ , respectively. We draw a parallel with the work of Fonseca, Fusco & Marcellini [27], [28], by establishing

Theorem 1.8. Let  $u \in W^{2,p}(\Omega)$ . If p > N-1 and if  $\mathcal{F}_H(u,\Omega,(W^{2,p},w)) < \infty$  then there exists a Radon measure  $\mathcal{R}_H(u,\cdot)$  such that

$$\mathcal{R}_H(u, U) = \mathcal{F}_H(u, U, (W^{2,p}, w))$$

for every open set  $U \subset \Omega$ . If  $p > \frac{N^2}{N+2}$  and if  $\mathcal{F}_H(u,\Omega,(W^{2,p},w)) < \infty$  then  $\mathcal{H}u = \mathcal{H}_2^*u$  is a Radon measure and its total variation measure satisfies the inequality

$$|\mathcal{H}u| \le \mathcal{F}_H(u,\cdot,(W^{2,p},w)).$$

Again here we remark that often we cannot reduce these second order problems to the first order setting. To illustrate this, we exhibit two examples on which

$$\mathcal{F}_J(\nabla u, B(0,1), (W^{1,p}, w)) = 0 < \mathcal{H}(u)(B(0,1)) \le \mathcal{F}_H(u, B(0,1), (W^{2,p}, w)),$$

where for q = d = N, k = 1,  $\mathcal{F}_J$  stands for the relaxation of

$$u \mapsto \int_{U} |\det \nabla u| \, dx.$$

Theorem 1.9. Suppose that  $N-1 \ge p > N^2/(N+2)$ . Then there exists a function  $u \in W^{2,p}(B(0,1))$  such that

$$\mathcal{R}_J(\nabla u, \cdot) = 0 \neq \mathcal{H}u = |\mathcal{H}u| \leq \mathcal{R}_H(u, \cdot)$$

If p = N - 1 then the first inequality in Theorem 1.9 was established by Acerbi & Dal Maso [1] with u(x) := |x| (thus  $\nabla u(x) = \frac{x}{|x|}$ ), while if p < N - 1 then Malý [47] proved that the first inequality holds for the smooth function  $u(x) = |x|^2$ . In both cases the inequality  $\mathcal{H}(u)(B(0,1)) > 0$  is obtained by direct inspection.

Finally, we recall the class of functions considered in Fonseca, Fusco & Marcellini [28]. Let  $B(0,1) \subset \mathbb{R}^2$  be the unit ball, and suppose that  $u: B \to \mathbb{R}^2$  is a zero homogenous function of type

$$u(re^{-it}) := \xi(t),$$

where  $\xi:\mathbb{R}\to\mathbb{C}$  is a  $2\pi$ -periodic function. Then it can be shown that

(9) 
$$\operatorname{Det} u = c\delta_0, \text{ with } c = \int\limits_{\mathbb{R}^2} \operatorname{Ind}_{\xi} z \, dz_1 \, dz_2,$$

whereas  $\mathcal{F}_J(u,\cdot,(W^{1,p},w))$  with p>1 is a Radon measure  $\mathcal{R}_J(u,\cdot)$  and

(10) 
$$\mathcal{R}_J(u,\cdot) = c'\delta_0 \text{ with } c' \geq \int\limits_{\mathbb{R}^2} |\mathrm{Ind}_{\xi}z| \, dz_1 \, dz_2.$$

It is clear, therefore, that cancellations may occur when computing |Det u| and an example of strict inequality

$$|\text{Det } u|(B(0,1)) < \mathcal{R}_J(u,B(0,1))$$

may be easily found.

Notice that the inequality in (10) can be strict. The example is based on an «eight like curve» invented originally in connection with the theory of Cartesian currents, see Malý [46], Giaquinta, Modica and Souček [35], [36], Mucci [50].

There is a two-dimensional example of a function  $u \in W^{2,p}(B), p > 1$ , the so-called «fish-like example» such that

$$\nabla u(re^{-it}) = \xi(t),$$

where  $\xi$  is a  $2\pi$ -periodic curve,

$$\mathcal{H}u = c\delta_0, \qquad \mathcal{R}_H(u,\cdot) = c'\delta_0$$

and

$$c' > c > 0$$
.

As a consequence we obtain

Theorem 1.10. Suppose that N=2 and  $1 . Then there exists a function <math>u \in W^{2,p}(B(0,1))$  such that  $|\mathcal{H}u| \neq \mathcal{R}_H(u,\cdot)$ .

The fish-like example will be explained in a subsequent paper [33].

## 2 - Continuity properties of the distributional Hessian. The Proofs of Theorems 1.3 and $1.4\,$

The proof of Theorem 1.3 is identical to that of Dacorogna & Murat [23] for  $p > N^2/(N+2)$ . For completeness we recall it below.

Proof of Theorem 1.3 Suppose first that N = 2 and let  $\{u_n\}$  be a sequence of

functions converging to u strongly in  $W^{1,2}(\Omega)$ . If  $\varphi \in C_c^{\infty}(\Omega)$  then clearly

$$\langle \mathcal{H}u_n, \varphi \rangle \to \langle \mathcal{H}u, \varphi \rangle.$$

If  $N \geq 3$ , then let  $\{u_n\}$  be a sequence of functions converging to u strongly in  $W^{1,s}(\Omega)$  and weakly in  $W^{2,p}(\Omega)$ . Fix  $\varphi \in C_c^{\infty}(\Omega)$  and write

$$\langle \mathcal{H}u_n, arphi 
angle = -rac{1}{N!} \sum_{p,q \in P} \operatorname{sgn} p \operatorname{sgn} q \int\limits_{\Omega} D_{p_1} u_n D_{q_1} u_n D_{p_2 q_2} arphi D_{p_3 q_3} u_n \dots D_{p_N q_N} u_n \, dx.$$

We have

$$D_{p_1}u_nD_{q_1}u_n \to D_{p_1}uD_{q_1}u$$
 in  $L^{s/2}$ ,

and, using the well know theory of weak convergence of minors, we obtain

$$dD_{p_3}u_n \wedge \ldots \wedge dD_{p_N}u_n \rightharpoonup dD_{p_3}u \wedge \ldots \wedge dD_{p_N}u$$

weakly in  $L^{p/(N-2)}$  (or weakly\* in the sense of measures if p=N-2). Thus we conclude immediately that

$$\langle \mathcal{H}u_n, \varphi \rangle \to \langle \mathcal{H}u, \varphi \rangle.$$

Next,

Proof of Theorem 1.4. If  $p \ge N$  then the result is trivial as  $\mathcal{H}(u)$  reduces to  $\det \nabla^2 u \in L^{p/N}(\Omega)$ . Suppose now that p < N.

Step 1. We treat first the case where N=2. Let  $x_0 \in \Omega$  be a Lebesgue point for u, for the absolutely continuous part  $\nabla^2 u$  of  $D^2 u$  and is such that  $(D^2 u)_s(B(x_0,\varepsilon))=o(\varepsilon^N)$  as  $\varepsilon\to 0$ . We write  $u(x)=:u(x_0)+\nabla u(x_0)(x-x_0)+\frac{1}{2}\nabla^2 u(x_0)(x-x_0)\cdot (x-x_0)+v(x)$ , so that

(11) 
$$\lim_{\varepsilon \to 0} \frac{1}{\varepsilon^2} \int_{B(x_0,\varepsilon)} |\nabla v(x)| \, dx = 0 \quad \text{and } \lim_{\varepsilon \to 0} \frac{\left| D^2 v(B(x_0,\varepsilon)) \right|}{\varepsilon^2} = 0.$$

We abbreviate

$$A(x) := u(x_0) + \nabla u(x_0)(x - x_0),$$
  

$$Q(x) := \frac{1}{2} \nabla^2 u(x_0)(x - x_0) \cdot (x - x_0).$$

Then u = A + Q + v and

$$(\mathcal{H}u*\psi_{\varepsilon})(x_0) = -\frac{1}{2} \sum_{p,q \in P} \operatorname{sgn} p \operatorname{sgn} q \int_{\Omega} D_{p_1} u D_{q_1} u D_{p_2 q_2} \psi_{\varepsilon}(x_0 - x) dx$$
$$= (\mathcal{H} Q * \psi_{\varepsilon})(x_0) + \mathcal{R}_{\varepsilon}$$
$$= \det \nabla^2 u(x_0) + \mathcal{R}_{\varepsilon}.$$

where

$$\mathcal{R}_{arepsilon} = -rac{1}{2} \sum_{p \in P} \operatorname{sgn} p \mathcal{R}_{arepsilon,p} \quad ext{with} \quad R_{arepsilon,p} = L^1_{arepsilon} + L^2_{arepsilon} + L^3_{arepsilon} + L^4_{arepsilon} + L^5_{arepsilon},$$

and for a fixed permutation p of  $\{1,2\}$  we have

$$egin{aligned} L^1_arepsilon &:= \int_{arOmega} D_{p_1} A \, du \wedge dD_{p_2} oldsymbol{\psi}_arepsilon, \ L^2_arepsilon &:= \int_{arOmega} D_{p_1} (Q+v) \, dA \wedge dD_{p_2} oldsymbol{\psi}_arepsilon, \ L^3_arepsilon &:= \int_{arOmega} D_{p_1} Q \, dv \wedge dD_{p_2} oldsymbol{\psi}_arepsilon, \ L^4_arepsilon &:= \int_{arOmega} D_{p_1} v \, dQ \wedge dD_{p_2} oldsymbol{\psi}_arepsilon, \end{aligned}$$

and

$$L^5_arepsilon := \int\limits_\Omega D_{p_1} v \, dv \wedge dD_{p_2} \psi_arepsilon.$$

We claim that  $\mathcal{R}_{\epsilon} \to 0$  as  $\epsilon \to 0$ . Indeed,

$$L_{c}^{1}=0$$

because

$$\int\limits_{\Omega}du\wedge d\eta=0\quad\text{for all }\eta\in C_{\rm c}^{\infty}(\Omega),$$

and since

$$L^2_arepsilon := \int\limits_{arOmega} \!\! D_{p_1} u \, dA \wedge dD_{p_2} \psi_arepsilon,$$

collecting all terms of type  $I_{\varepsilon}^2$  together we notice that

$$\sum_{p,q\in P} \operatorname{sgn} p \operatorname{sgn} q \int\limits_{\varOmega} D_{p_1} u D_{q_1} A D_{p_2q_2} \psi_{\varepsilon} \, dx = \sum_{q\in P} \operatorname{sgn} q \int\limits_{\varOmega} D_{q_1} A du \wedge dD_{q_2} \psi_{\varepsilon} = 0,$$

where in the last equality we used the same argument as for  $L^1_{\varepsilon}$ .

Using the fact that  $\|\nabla^2\psi_{\varepsilon}\|_{L^{\infty}}\leq C/\varepsilon^4$  and that  $\|\nabla Q\|_{L^{\infty}}\leq \varepsilon$ , we have

$$\left|L_{\varepsilon}^{3}\right|+\left|L_{\varepsilon}^{4}\right|\leq\frac{C}{\varepsilon}\int\limits_{B(x_{0},\varepsilon)}\left|\nabla v(x)\right|dx\leq C\lim_{\varepsilon\rightarrow0}\frac{\left|D^{2}v(B(x_{0},\varepsilon))\right|}{\varepsilon^{2}}\rightarrow0,$$

by (11), and where we used Poincaré's inequality in BV (see [5] (3.42)), and the fact that in  $L^3_\varepsilon$  we could have written  $v-\int\limits_{B(x_0,\varepsilon)}v(y)\,dy$  in place of v (the same applies to  $L^4_\varepsilon$  and  $L^5_\varepsilon$ ). Finally

$$\left|L_{\varepsilon}^{5}\right| \leq \frac{C}{\varepsilon^{2}} \int\limits_{B(x_{0},\varepsilon)} \left|\nabla v(x)\right|^{2} dx \leq C \lim_{\varepsilon \to 0} \frac{\left|D^{2} v(B(x_{0},\varepsilon))\right|}{\varepsilon^{2}} \to 0,$$

by the Sobolev-Poincaré inequality since here  $p^* = 1^* = 2$ .

 $Step\ 2.\ \text{Let}\ N\geq 3\ \text{and assume that}\ \frac{N^2}{N+2}\leq p< N.\ \text{Consider a point}\ x_0\in \Omega\ \text{which}$  is a \$p\$-Lebesgue point for \$u\$, \$\nabla u\$ and \$\nabla^2 u\$. As in Step 1 we write \$u(x)=:u(x\_0)\$  $+\nabla u(x_0)(x-x_0)+\frac{1}{2}\nabla^2 u(x_0)(x-x_0)\cdot (x-x_0)+v(x)=A(x)+Q(x)+v(x), \text{ so that}$ 

(12) 
$$\lim_{\varepsilon \to 0} \frac{1}{\varepsilon^N} \int_{B(x_0,\varepsilon)} \left| \nabla^2 v(x) \right|^p dx = 0, \qquad \lim_{\varepsilon \to 0} \frac{1}{\varepsilon^N} \int_{B(x_0,\varepsilon)} \left| \nabla v(x) \right|^p dx = 0.$$

Just as above

$$\begin{split} (\mathcal{H}u * \psi_{\varepsilon})(x_0) &= -\frac{1}{N!} \sum_{p,q \in P} \operatorname{sgn} p \operatorname{sgn} q \int_{\Omega} D_{p_1} u D_{q_1} u D_{p_2 q_2} \psi_{\varepsilon}(x_0 - x) D_{p_3 q_3} u \dots D_{p_N q_N} u \, dx \\ &= (\mathcal{H} Q * \psi_{\varepsilon})(x_0) + \mathcal{R}_{\varepsilon} \\ &= \det \nabla^2 u(x_0) + \mathcal{R}_{\varepsilon}, \end{split}$$

where now

$$\mathcal{R}_{arepsilon} = -rac{1}{N!} \sum_{p \in P} \operatorname{sgn} p \; R_{arepsilon,p} \quad ext{and} \; R_{arepsilon,p} := I_{arepsilon}^1 + I_{arepsilon}^2 + I_{arepsilon}^3 + I_{arepsilon}^4 + I_{arepsilon}^5 + I_{arepsilon}^6,$$

and for a fixed permutation p of  $\{1, \ldots, N\}$  we have

$$egin{aligned} I^1_arepsilon &:= \int\limits_\Omega D_{p_1} A \ du \wedge dD_{p_2} \psi_arepsilon \wedge dD_{p_3} u \wedge \ldots \wedge dD_{p_N} u, \ I^2_arepsilon &:= \int\limits_\Omega D_{p_1} (Q+v) \ dA \wedge dD_{p_2} \psi_arepsilon \wedge dD_{p_3} u \wedge \ldots \wedge dD_{p_N} u, \end{aligned}$$

$$egin{aligned} I_{arepsilon}^3 &:= \int\limits_{\Omega} D_{p_1} Q \, dQ \wedge dD_{p_2} \psi_{arepsilon} \wedge dD_{p_3} u \wedge \ldots \wedge dD_{p_N} u \ &- \int\limits_{\Omega} D_{p_1} Q \, dQ \wedge dD_{p_2} \psi_{arepsilon} \wedge dD_{p_3} Q \wedge \ldots \wedge dD_{p_N} Q, \ &I_{arepsilon}^4 &:= \int\limits_{\Omega} D_{p_1} Q \, dv \wedge dD_{p_2} \psi_{arepsilon} \wedge dD_{p_3} u \wedge \ldots \wedge dD_{p_N} u, \ &I_{arepsilon}^5 &:= \int\limits_{\Omega} D_{p_1} v \, dQ \wedge dD_{p_2} \psi_{arepsilon} \wedge dD_{p_3} u \wedge \ldots \wedge dD_{p_N} u, \end{aligned}$$

and

$$I^6_arepsilon := \int\limits_{\Omega} D_{p_1} v \, dv \wedge dD_{p_2} \psi_arepsilon \wedge dD_{p_3} u \wedge \ldots \wedge dD_{p_N} u.$$

In order to prove that  $\mathcal{R}_\epsilon \to 0$  as  $\epsilon \to 0,$  we observe first that

$$I_{c}^{1}=0$$

because

$$\int\limits_{\Omega}du\wedge d\eta\wedge dD_{p_3}u\wedge\ldots\wedge dD_{p_N}u=0\quad ext{for all }\eta\in C^\infty_{
m c}(\Omega).$$

Also, since

$$\int\limits_{Q} D_{p_1} A \, dA \wedge dD_{p_2} \psi_{arepsilon} \wedge dD_{p_3} u \wedge \ldots \wedge dD_{p_N} u = 0,$$

we have

$$I_arepsilon^2 := \int\limits_{\Omega} D_{p_1} u \, dA \wedge dD_{p_2} \psi_arepsilon \wedge dD_{p_3} u \wedge \ldots \wedge dD_{p_N} u,$$

and collecting all terms of type  $I_{\varepsilon}^2$  together we notice that

$$egin{aligned} &\sum_{p,q\in P} \operatorname{sgn} q \int\limits_{\Omega} D_{p_1} u D_{q_1} A D_{p_2q_2} \psi_{arepsilon} D_{p_3q_3} u \dots D_{p_Nq_N} u \, dx \ \\ &= \sum_{q\in P} \operatorname{sgn} q \int\limits_{\Omega} D_{q_1} A \, du \wedge dD_{q_2} \psi_{arepsilon} \wedge \, dD_{q_3} u \dots \wedge dD_{q_N} u = 0, \end{aligned}$$

where in the last equality we used the same argument as for  $I_{\varepsilon}^1$ .

Using the fact that  $\|\nabla^2 \psi_{\varepsilon}\|_{L^{\infty}} \leq C/\varepsilon^{N+2}$  and that  $\|\nabla Q\|_{L^{\infty}} \leq \varepsilon$ , we have

$$\left|I_{\varepsilon}^{3}\right| \leq C \sum_{k=1}^{N-2} \int\limits_{B(x_{0,\varepsilon})} \left|\nabla^{2} v(x)\right|^{k} dx \to 0$$

by (12). Also, noting that in  $I_{\varepsilon}^4$ ,  $I_{\varepsilon}^5$  and  $I_{\varepsilon}^6$  we could have written  $v-\int v(y)\,dy$  in place

of v, using Poincaré's inequality and the fact that  $\frac{1}{p*} + \frac{N-2}{p} \le 1$ , with  $p* := \frac{Np}{N-p}$ , we have

$$\begin{split} \left|I_{\varepsilon}^{4}\right| &\leq \frac{C}{\varepsilon} \int\limits_{B(x_{0},\varepsilon)} \left|\nabla v\right| \left|\nabla^{2} u\right|^{N-2} dx \\ &\leq \frac{C}{\varepsilon} \Big(\int\limits_{B(x_{0},\varepsilon)} \left|\nabla v\right|^{p*} dx \Big)^{1/p*} \Big(\int\limits_{B(x_{0},\varepsilon)} \left|\nabla^{2} u\right|^{p} dx \Big)^{(N-2)/p} \\ &\leq C \Big(\int\limits_{B(x_{0},\varepsilon)} \left|\nabla^{2} v\right|^{p} dx \Big)^{1/p} \Big(\int\limits_{B(x_{0},\varepsilon)} \left|\nabla^{2} u\right|^{p} dx \Big)^{(N-2)/p}. \end{split}$$

The boundedness of  $\int\limits_{B(x_0,\varepsilon)} |\nabla^2 u|^p\,dx$  and (12) yield

$$\lim_{\varepsilon \to 0} I_{\varepsilon}^4 = 0.$$

It can be seen easily that  $I_{\varepsilon}^5$  may be treated as  $I_{\varepsilon}^4$ , and since  $\frac{2}{p*} + \frac{N-2}{p} \leq 1$ ,

$$\begin{split} \left|I_{\varepsilon}^{6}\right| &\leq \frac{C}{\varepsilon^{2}} \int\limits_{B(x_{0},\varepsilon)} \left|\nabla v\right|^{2} \left|\nabla^{2} u\right|^{N-2} dx \\ &\leq C \left[\frac{1}{\varepsilon} \left(\int\limits_{B(x_{0},\varepsilon)} \left|\nabla v\right|^{p*} dx\right)^{1/p*}\right]^{2} \left(\int\limits_{B(x_{0},\varepsilon)} \left|\nabla^{2} u\right|^{p} dx\right)^{(N-2)/p} \\ &\leq C \left(\int\limits_{B(x_{0},\varepsilon)} \left|\nabla^{2} v\right|^{p} dx\right)^{2/p} \left(\int\limits_{B(x_{0},\varepsilon)} \left|\nabla^{2} u\right|^{p} dx\right)^{(N-2)/p} \to 0, \end{split}$$

and this concludes the proof.

### 3 - Relaxation of variational integrals. The Proofs of Theorems 1.7 and 1.8

In this section we follow the arguments introduced in Fonseca & Malý [32] and in Bouchitté, Fonseca & Malý [12], and we divide the proof into the two propositions below.

Proposition 3.1. Let F satisfy (7) with (8). Suppose that  $u \in W^{k,p}(\Omega; \mathbb{R}^d)$  and  $\mathcal{F}(u,\Omega,(W^{k,p},w)) < \infty$ . Then there exists a Radon measure  $\mathcal{R}(u,\cdot)$  on  $\Omega$  such that

$$\mathcal{R}(u, U) = \mathcal{F}(u, U, (W^{k,p}, w))$$

for each open set  $U \subset \Omega$ . Moreover, if  $\gamma > 0$  then there exists a «minimizing» sequence  $\{u_n\}$  of smooth functions such that  $u_n \rightharpoonup u$  in  $W^{k,p}(\Omega; \mathbb{R}^d)$  and

$$F(u_n,\cdot) \stackrel{*}{\rightharpoonup} \mathcal{R}(u,\cdot)$$
 in the sense of measures.

Proposition 3.2. Let F satisfy (7) with (8). Suppose that  $u \in W^{k,p}(\Omega, \mathbb{R}^d)$  and  $\mathcal{F}(u, \Omega, (W^{k,p}, w)) < \infty$ . Then

$$\frac{d\mathcal{R}(u,\cdot)}{d\mathcal{L}^N}(x) = Q_k f(x) \quad \text{a.e. in } \Omega.$$

Proof of Proposition 3.1. There is no novelty here as compared with the results of [32], and so we limit ourselves to present a road map of the proof following that paper: Reproduce Theorem 3.2 in [32] with the obvious adaptations. This theorem uses the subbaditivity established in Lemma 3.4 in [32], and, in turn, this needs a delicate process of gluing to energy bounded sequences converging to the same target on a small layer with vanishing energy. This is accomplished in Lemma 2.4 in [32], and here is where we must replace the then used projection operator by our new trace preserving operator T. The positive exponent  $\tau$  in Lemma 2.4 now reads

$$\tau := \frac{N}{q} - \frac{N-1}{p}.$$

Concerning now Proposition 3.2, and in order to prove the inequality

$$\frac{d\mathcal{R}(u,\cdot)}{d\mathcal{L}^N}(x) \ge Q_k f(x) \quad \text{a.e. in } \Omega,$$

we could have tried to show directly that if  $u_n \rightharpoonup u$  in  $W^{k,p}(\Omega;\mathbb{R}^d)$  then

$$\int\limits_{\varOmega}Q_kf(\nabla^ku)\,dx\leq \liminf\limits_{n\to\infty}\int\limits_{\varOmega}f(\nabla^ku_n)\,dx.$$

Here we are tempted to use the results in [24] to reduce this to the 1-quasiconvexity setting and then apply the lowersemicontinuity result of Fonseca & Malý [32] for 1-quasiconvex functions within the gap range of (8). However, this is not possible as (see Theorems 1.2 and 1.3 in [24]) in order to obtain the (approximate) extensions of the k-quasiconvex envelope of f to 1-quasiconvex functions, we would need to consider q-coercive perturbations of f,  $f_{\varepsilon} := f + \varepsilon |\cdot|^q$ , and we do not have an uniform bound for  $\|\nabla^k u_n\|_{L^q}$ .

An important tool to prove Proposition 3.2 will be the trace preserving operator T

that will play the role of the projection operator introduced in [32] and later used in [12]. This operator could be constructed via an argument similar to that of Th. 3.6.2 in [62], however here we opt for a method using Whitney balls. In what follows, we denote  $\rho(x) = \text{dist}(x, \mathbb{R}^N \setminus \Omega)$ . We recall that a countable collection  $\mathcal{W} = \{B_i\}_i$  of open balls is called a family of Whitney balls for  $\Omega$ , if (see e.g. [20]) (W1) if  $B(x, r) \in \mathcal{W}$ , then  $10r = \rho(x)$ .

- (W2) the family  $\mathcal{W}$  covers  $\Omega$ ;
- (W3) the family  $\{B(x,4r): B(x,r) \in \mathcal{W}\}$  has a bounded overlap multiplicity by a constant depending only on N.

Let  $\{\omega_i\}_i$  be a partition of unity subordinated to  $\mathcal{W}$ , i.e.  $\omega_i$  are nonnegative smooth functions,  $\sum_i \omega_i = 1$  in  $\Omega$ ,  $B(x_i, r_i) \subset \operatorname{spt}\omega_i \subset B(x_i, 2r_i)$ , and

$$|\nabla^j \omega_i| \le C_i / r_i^j, \qquad j = 1, 2 \dots$$

The construction of  $\omega_i$  is the following: Let  $\tilde{\omega}$  be a smooth cutoff function between B(0,1) and B(0,2) and set

$$\tilde{\omega}_i(x) := \tilde{\omega}\left(\frac{x - x_i}{r_i}\right), \qquad i = 1, 2, \dots$$

Define

$$\omega_1 := \tilde{\omega}_1,$$

$$\omega_i := \tilde{\omega}_i (1 - \tilde{\omega}_1) \dots (1 - \tilde{\omega}_{i-1}), \qquad i = 2, 3, \dots.$$

The estimate (13) follows from the bounded overlap multiplicity of W, so that the product defining  $\omega_i$  has a bounded number of factors different from 1.

Denote  $\Omega_{\varepsilon}:=\{x\in\Omega: \mathrm{dist}(x,\partial\Omega)>\varepsilon\},\ \varepsilon>0,\ \mathrm{and\ consider\ a\ family\ }\{\varphi_{\varepsilon}\}_{\varepsilon>0}\ \mathrm{of\ mollifiers\ such\ that\ }\varphi_{\varepsilon}\ \mathrm{are\ functions\ in\ }C_{\varepsilon}^{\infty}(\mathbb{R}^{N})\ \mathrm{with\ support\ in\ }\overline{B}(0,\varepsilon),\ \mathrm{as\ it\ is\ usual\ }\varphi_{\varepsilon}\ \mathrm{obey\ the\ scaling\ rule}$ 

$$\varphi_{\varepsilon}(x) = \varepsilon^{-N} \varphi_{I}(\chi/\varepsilon), \qquad \chi \in \mathbb{R}^{N}, \ \varepsilon > 0,$$

and the property

$$(14) \varphi_c * P = P$$

is satisfied for every polynomial P of degree  $\leq k$  and all  $\varepsilon > 0$  (for the existence of  $\{\varphi_{\varepsilon}\}$  see Lemma 3.5.6. in [62]). Remark that, in view of (14), we cannot assume that these mollifiers are nonnegative. Given  $u \in W^{1,p}(\Omega)$ , for each  $i \in \mathbb{N}$  let

$$T_i u := \left\{ egin{array}{ll} arphi_{r_i} st u & ext{in } arOmega_{r_i}, \ 0 & ext{elsewhere}, \end{array} 
ight.$$

and set

$$Tu := \sum_{i} \omega_i \ T_i u.$$

Notice that the jump of  $T_i u$  is far from the support of  $\omega_i$ , so that Tu is smooth in  $\Omega$ . Indeed,

supp 
$$\omega_i \subset B(x_i, 2r_i) \subset B(x_i, 9r_i) \subset \Omega_{r_i}$$
.

Theorem 3.3. Let 1 p. Then the operator T has the following properties:

$$(\mathrm{T1}) \ |\nabla^l T u(x)| \leq C \int\limits_{B(x_i,3r_i)} |\nabla^l u| \ dy \ \text{if} \ u \in W^{k,p}(\varOmega), \ x \in B(x_i,r_i), \ l = 0,1 \ldots, k;$$

$$\text{(T2)} \ \Big( \int\limits_{B(x_i,r_i)} \left| \nabla^l T u \right|^q dx \Big)^{1/q} \leq C \Big( \int\limits_{B(x_i,3r_i)} \left| \nabla^l u \right|^p dx \Big)^{1/p} \ \text{if} \ u \in W^{k,p}(\varOmega), \ l = 0, \ldots, k;$$

(T3)  $T: W^{k,p}(\Omega) \to W^{k,p}(\Omega)$  is a bounded linear operator;

(T4) if 
$$u \in W^{k,p}(\Omega)$$
 then  $Tu - u \in W_0^{k,p}(\Omega)$ ;

$$(\text{T5}) \left( \int\limits_{\Omega \setminus \Omega_{\varepsilon}} |\nabla^{k} \, Tu|^{q} \, dx \right)^{1/q} \leq C \varepsilon^{\frac{N}{q} - \frac{N-1}{p}} \sup_{0 < \delta \leq 2\varepsilon} \delta^{-1/p} \Big( \int\limits_{\Omega \setminus \Omega_{\delta}} |\nabla^{k} u|^{p} \, dx \Big)^{1/p} \text{ for } u \in W^{k,p}(\Omega).$$

**Proof.** Step 1. Suppose that  $B(x_i, 2r_i) \cap B(x_i, 2r_i) \neq \emptyset$ . Then

$$10r_j = \rho(x_j) \le \rho(x_i) + |x_i - x_j| \le 10r_i + 2r_i + 2r_j,$$

and it follows that

(15) 
$$r_{j} \leq \frac{3}{2}r_{i},$$

$$B(x, r_{i}) \subset B(x_{i}, r_{i} + r_{i}) \subset B(x_{i}, 3r_{i}), \qquad x \in B(x_{i}, r_{i}).$$

Interchanging the roles of i and j, we also have

$$(16) r_i \le \frac{3}{2}r_j.$$

Suppose that  $x \in B(x_i, r_i)$  and that

$$j \in I(i) := \{j : B(x_i, 2r_i) \cap B(x_i, r_i) \neq \emptyset\}.$$

Notice that by the property (W3) of the Whitney covering,

$$\# I(i) \le C.$$

Then for  $l \in \{0, \dots, k\}$  we have

$$\nabla^{l} T u(x) = \sum_{m=0}^{l} \sum_{j} C_{m} \nabla^{l-m} \omega_{j}(x) (\varphi_{r_{j}} * \nabla^{m} u)(x)$$

$$= \sum_{m=0}^{l} \sum_{i \in I(i)} C_{m} \nabla^{l-m} \omega_{j}(x) (\varphi_{r_{j}} * (\nabla^{m} u - P_{m}))(x)$$

for some constants  $C_m \in \mathbb{R}$  and certain polynomials  $P_m$  of order l-m-1 for which the Poincaré inequality

(18) 
$$\int_{B(x_{i},3r_{i})} |\nabla^{m}u - P_{m}| \, dy \le Cr_{i}^{l-m} \int_{B(x_{i},3r_{i})} |\nabla^{l}u| \, dy$$

holds (set P = 0 if m = l). Note that here we used the fact that, by virtue of (14), we can write

$$\begin{split} \sum_{j\in I(i)} \nabla^{l-m} \omega_j(x) \ (\varphi_{r_i} * P_m)(x) &= \sum_{j\in I(i)} \nabla^{l-m} \omega_j(x) \ P_m(x) \\ &= P_m(x) \nabla^{l-m} \sum_i \omega_j(x) = P_m(x) \nabla^{l-m} 1 = 0. \end{split}$$

Using (13), (16), (17) and (18) we now have

$$\begin{split} |\nabla^{l} T u(x)| &\leq C \sum_{m=0}^{l} \sum_{j \in I(i)} \left| \nabla^{l-m} \omega_{j} (\varphi_{r_{i}} * (\nabla^{m} u - P_{m})) \right| (x) \\ &\leq C \sum_{m=0}^{l} \sum_{j \in I(i)} r_{j}^{m-l} \int\limits_{B(x,r_{j})} \left| \nabla^{m} u - P_{m} \right| (y) \, dy \\ &\leq C \sum_{m=0}^{l} r_{i}^{m-l} \int\limits_{B(x_{i},3r_{i})} \left| \nabla^{m} u - P_{m} \right| (y) \, dy \\ &\leq C \int\limits_{B(x_{i},3r_{i})} \left| \nabla^{l} u \right| \, dy. \end{split}$$

Step 2. (T2) is an obvious consequence of (T1).

Step 3. A standard application of the properties of the Whitney covering and of (T2) with the choice q = p yields (T3).

Step 4. Property (T4) follows from (T3) and from the fact that

$$Tu - u = \lim_{j \to \infty} \sum_{i=1}^{j} \omega_i (T_i u - u).$$

Step 5. To prove (T5), set

$$M:=\sup_{0<\delta\leq 2arepsilon}\delta^{-1/p}\Bigl(\int\limits_{arOptimes_{Q}\setminus arOptimes_{Q}}|
abla^ku|^p\,dx\Bigr)^{1/p}.$$

If  $x \in B(x_i, r_i) \setminus \Omega_{\varepsilon}$  then

$$10r_i = \operatorname{dist}(x_i, \partial \Omega) \le \operatorname{dist}(x, \partial \Omega) + |x_i - x| \le r_i + \varepsilon$$

and so  $9r_i \le \varepsilon$ . We have by (T2)

$$\begin{split} & \left( \int\limits_{\Omega \setminus \Omega_{\varepsilon}} |\nabla^{k} \, Tu|^{q} \, dx \right)^{1/q} \leq \left( \sum_{j=3}^{\infty} \sum_{\{i:2^{-j-1} < \frac{r_{i}}{\varepsilon} < 2^{-j} \}} \int\limits_{B(x_{i},r_{i})} |\nabla^{k} \, Tu|^{q} \, dx \right)^{1/q} \\ & \leq C \left( \sum_{j=3}^{\infty} \sum_{\{i:2^{-j-1} < \frac{r_{i}}{\varepsilon} < 2^{-j} \}} r_{i}^{N(1-\frac{q}{p})} \left( \int\limits_{B(x_{i},3r_{i})} |\nabla^{k} \, u|^{p} \, dx \right)^{q/p} \right)^{1/q} \\ & \leq C \left( \sum_{j=3}^{\infty} (2^{-j} \varepsilon)^{N(1-\frac{q}{p})} \left( \sum_{\{i:2^{-j-1} < \frac{r_{i}}{\varepsilon} < 2^{-j} \}} \int\limits_{B(x_{i},3r_{i})} |\nabla^{k} \, u|^{p} \, dx \right)^{q/p} \right)^{1/q} \\ & \leq C \left( \sum_{j=3}^{\infty} (2^{-j} \varepsilon)^{N(1-\frac{q}{p})} \left( \int\limits_{\Omega \setminus \Omega_{2^{4-j}\varepsilon}} |\nabla^{k} \, u|^{p} \, dx \right)^{q/p} \right)^{1/q} \\ & \leq C \left( \sum_{j=1}^{\infty} (2^{-j} \varepsilon)^{N(1-\frac{q}{p})} (2^{-j} \varepsilon)^{\frac{q}{p}} M^{\frac{q}{p}} \right)^{1/q} \\ & \leq C \varepsilon^{\frac{N-N-1}{p}} M^{\frac{1}{p}}, \end{split}$$

where we used the facts that if  $x \in B(x_i, 3r_i)$  for some  $r_i$  such that  $2^{-j-1} < \frac{r_i}{\varepsilon} < 2^{-j}$  then

$$\operatorname{dist}(x,\partial\Omega) \leq \operatorname{dist}(x_i,\partial\Omega) + |x_i - x| \leq 10r_i + 3r_i < 2^{4-j}\varepsilon,$$

and

$$\sum_{j=1}^{\infty} 2^{-j(\frac{N}{q} - \frac{N-1}{p})} < +\infty$$

in view of (8).  $\Box$ 

The proof of Proposition 3.2 follows closely the proof of Theorem 3.1 in [12] with the obvious modifications, where (3.17) is

(19) 
$$\frac{d\mathcal{R}(u,\cdot)}{d\mathcal{L}^N}(x_0) = \lim_{r \to 0} \frac{\boldsymbol{m}(u, B(x_0, r))}{\mathcal{L}^N(B(x_0, r))},$$

and where the limit is taken on a «good» sequence of radii. Here, when  $B\subset\subset\Omega$  is an open ball, we set

$$m(u, B) = \inf \{ F(v, B) : v \in W^{k, q}(B; \mathbb{R}^d), \ v - u \in W_0^{k, q}(B; \mathbb{R}^d) \}.$$

Proposition 3.2, similarly to Theorem 3.1 in [12], now seats on Proposition 3.1, and on the analogs of Lemmas 3.6 and 3.7 in [12], that now read as, respectively

Lemma 3.4. Suppose that  $u \in W^{k,p}(\Omega; \mathbb{R}^d)$  and  $\mathcal{F}(u, \Omega, (W^{k,p}, w)) < \infty$ . Let  $B(x_0, R_0) \subset \Omega$ . Then

(20) 
$$\mathbf{m}(u, B(x_0, r_0)) < \mathcal{F}(u, B(x_0, r_0), (W^{k,p}, w))$$

holds for  $\mathcal{L}^1$  a.e.  $r_0 \in (0, R_0)$ .

Lemma 3.5. Suppose that  $u \in W^{k,p}(\Omega; \mathbb{R}^d)$  and  $\mathcal{F}(u, \Omega, (W^{1,p}, w)) < \infty$ . Let  $B(x_0, R_0) \subset \Omega$ . Then  $\mathcal{L}^1$  a.e.  $r_0 \in (0, R_0)$  has the following property: If  $v \in W^{k,q}(B(x_0, r_0); \mathbb{R}^d)$  and  $u - v \in W^{k,p}_0(B(x_0, r_0); \mathbb{R}^d)$  then

(21) 
$$\mathcal{R}(w, \partial B(x_0, r_0)) = 0,$$

where

(22) 
$$w = \begin{cases} v & \text{in } B(x_0, r_0), \\ u & \text{outside } B(x_0, r_0). \end{cases}$$

So we are left with the proofs of Lemmas 3.4 and 3.5, and they both rely on a careful choice of radii provided by the following result.

Lemma 3.6. Suppose that  $u \in W^{k,p}(\Omega)$  and  $u_n \in W^{k,q}_{loc}(\Omega)$ ,  $u_n \rightharpoonup u$  in  $W^{k,p}(\Omega)$ . Let  $B(x_0,R_0)\subset \Omega$ . Then  $\mathcal{L}^1$  a.e.  $r_0\in (0,R_0)$  has the following property: For  $j=1,2,\ldots$ , there exist integers  $n_j\to\infty$ , radii  $r_j\nearrow r_0$ ,  $r'_j\searrow r_0$  and functions  $v_j\in W^{k,q}_{loc}(\Omega)$  such that  $v_j=u_{n_j}$  on  $\Omega\setminus \left(B(x,r'_j)\setminus B(x_0,r_j)\right)$ ,  $v_j-u\in W^{k,p}_0(B(x_0,r_0))$  and

$$\int\limits_{B(x_0,r_j')\setminus B(x_0,r_j)} \left|\nabla^k v_j\right|^q\,dx\to 0.$$

**Proof.** Using the Rellich-Kondrashev compact embedding theorem and passing if necessary to a subsequence (not relabeled), we may find  $a_n \to \infty$  and a Radon measure v on  $\Omega$  such that

$$|\nabla^k u_n|^p + |\nabla^k u|^p + a_n |\nabla^{k-1} (u_n - u)|^p + \dots + a_n |u_n - u|^p \stackrel{*}{\rightharpoonup} v$$

in the sense of measures.

We define a Radon measure  $\psi$  on  $(0, R_0)$  by

$$\psi(E) := v(\{x: |x - x_0| \in E\}), \qquad E \subset (0, R_0),$$

and denote

$$\phi(r) := \int\limits_{\partial B(x_0,r)} \left| 
abla^k u \right|^p dx, \quad 0 < r < R_0.$$

Let  $r_0 > 0$  be a radius such that the maximal functions of  $\phi$  and  $\psi$  are finite at  $r_0$ , i.e.

$$egin{aligned} M\phi(r_0) &= \sup_{0<\delta < r_0} rac{1}{\delta} \int\limits_{r_0-\delta}^{r_0+\delta} \phi(s)\,ds < +\infty, \ M\psi(r_0) &= \sup_{0<\delta < r_0} rac{\psi([r_0-\delta,r_0+\delta])}{\delta} < +\infty. \end{aligned}$$

We abbreviate

$$M := \max\{M\phi(r_0), M\psi(r_0)\}.$$

We first choose  $R_j, R'_j \in (0, R_0) \setminus \{r_0\}$ ,

$$R_j \nearrow r_0$$
,  $R'_i \searrow r_0$ ,  $R'_i - r_0 = r_0 - R_j$ .

Define

$$\phi_{n,j}(r) := \begin{cases} \int\limits_{\partial B(x_0,r)} (|\nabla^k u_n|^p + |\nabla^k u|^p \\ + a_n |\nabla^{k-1} (u_n - u)|^p + \dots + a_n |u_n - u|^p) \, dx & r \in [R_j, R'_j], \\ 0 & r \notin [R_j, R'_j]. \end{cases}$$

Set

$$E_{n,j}:=\{r\in(0,R_0): M\phi_{n,j}(r)>\lambda\},\quad \text{where }\lambda:=25(M+1).$$

Choose  $n_i$  so large that

$$(23) a_{n_i} \ge (R_i' - R_j)^{-pk}$$

and

(24) 
$$\int_{R_{j}}^{R'_{j}} \phi_{n,j}(r) dr = \int_{B(x_{0},R'_{j})\setminus B(x_{0},R_{j})} (|\nabla^{k}u_{n_{j}}|^{p} + |\nabla^{k}u|^{p} + a_{n_{j}}|\nabla^{k-1}(u_{n_{j}} - u)|^{p} + \dots + a_{n_{j}}|u_{n_{j}} - u|^{p}) dx$$
$$\leq \psi([R_{j}, R'_{j}]) + R'_{j} - R_{j} \leq (M+1)(R'_{j} - R_{j}).$$

By the Hardy-Littlewood maximal theorem, we deduce

(25) 
$$\mathcal{L}^{1}(E_{n,j}) \leq \frac{5}{\lambda} \int_{R_{j}}^{R'_{j}} \phi_{n,j}(r) dr \leq \frac{5}{\lambda} (M+1)(R'_{j} - R_{j}) = \frac{1}{5} (R'_{j} - R_{j}),$$

so that there exist

$$r_j \in \left(R_j, rac{1}{2}(R_j + r_0)
ight), \quad r_j' \in \left(rac{1}{2}(R_j' + r_0), \, R_j'
ight)$$

such that  $r_j, r'_i \notin E_{n,j}$ , and thus

(26) 
$$\max\{M\phi_{n,j}(r_j), M\phi_{n,j}(r'_j)\} \le \lambda.$$

With the choice  $n = n_i$ , define

$$\begin{split} A_j &:= B(x_0, r_j') \setminus \overline{B(x_0, r_j)}, \\ D_j &:= A_j \setminus \partial B(x_0, r_0), \\ v_j &:= \begin{cases} u_n & \text{on } \Omega \setminus A_j, \\ T^*u + (1 - \eta_j) \ T(u_n - u) & \text{on } A_j, \end{cases} \end{split}$$

where T is the trace preserving operator for  $A_j$ ,  $T^*$  is the trace preserving operator for  $D_j$  and  $\eta_j$  is a smooth cutoff function such that

$$\eta_j(x) = 1, \qquad |x - x_0| \le r_0 + \frac{1}{8}(R'_j - R_j),$$

$$\eta_j(x) = 0, \qquad |x - x_0| \ge r_0 + \frac{1}{4}(R'_j - R_j),$$

$$(r'_j - r_j)^i |\nabla^i \eta_j| \le C, \quad i = 1, \dots, k.$$

Note that the support of  $\eta_j$  is contained in  $A_j$  and that nearby  $\partial B(x_0,r_0)$  the function  $\eta_j=1$ , so that  $v_j\in W^{k,p}(\Omega)$  and  $v_j-u\in W^{k,p}_0(B(x_0,r_0))$ . We have

$$\begin{split} \left(\int\limits_{A_j} |\nabla^k v|^q \, dx\right)^{p/q} &\leq C \Big(\int\limits_{D_j} |\nabla^k T^* u|^q \, dx\Big)^{p/q} \\ &+ \Big(\int\limits_{A_j} |\nabla^k ((1-\eta_j)T(u_n-u))|^q \, dx\Big)^{p/q}. \end{split}$$

We observe that  $\operatorname{dist}(x, \partial D_j) \leq \operatorname{dist}(x, \partial A_j) < r'_j - r_j$  for every  $x \in D_j$ . Appealing to

the properties of the trace preserving operator, and using (26), we estimate

$$\begin{split} & \left( \int\limits_{D_{j}} |\nabla^{k} T^{*} u|^{q} \, dx \right)^{p/q} \\ & \leq C(r'_{j} - r_{j})^{N^{p}_{q} - (N-1)} \sup_{0 < \delta < 2(r'_{j} - r_{j})} \delta^{-1} \int\limits_{\{x \in D_{j} : \operatorname{dist}(x, \partial D_{j}) < \delta\}} |\nabla^{k} u|^{p} \, dx \\ & \leq C(r'_{j} - r_{j})^{N^{p}_{q} - (N-1)} \sup_{0 < \delta < 2(r'_{j} - r_{j})} [\delta^{-1} \int\limits_{B(x_{0}, r'_{j}) \setminus B(x_{0}, r'_{j} - \delta)} |\nabla^{k} u|^{p} \, dx \\ & + \delta^{-1} \int\limits_{B(x_{0}, r_{0} + \delta) \setminus B(x_{0}, r_{0} - \delta)} |\nabla^{k} u|^{p} \, dx + \delta^{-1} \int\limits_{B(x_{0}, r_{j} + \delta) \setminus B(x_{0}, r_{j})} |\nabla^{k} u|^{p} \, dx ] \\ & \leq C(r'_{j} - r_{j})^{N^{p}_{q} - (N-1)} (M\phi_{n, j}(r'_{j}) + M\phi(r_{0}) + M\phi_{n, j}(r_{j})) \\ & \leq C(r'_{j} - r_{j})^{N^{p}_{q} - (N-1)} (2\lambda + M) \to 0. \end{split}$$

Similarly, we have

$$\begin{split} & \left( \int\limits_{A_{j}} \nabla^{k} ((1-\eta_{j})T(u_{n}-u))|^{q} \, dx \right)^{p/q} \\ & \leq C \bigg( \int\limits_{A_{j}} (|\nabla^{k}Tu_{n}|^{q} + |\nabla^{k}Tu|^{q}) \, dx \bigg)^{p/q} \\ & + C \bigg( \sum_{i=1}^{k} (r'_{j}-r_{j})^{-qi} \int\limits_{A_{j}} (|\nabla^{k-i}T(u_{n}-u)|^{q}) \, dx \bigg)^{p/q} \\ & \leq C (r'_{j}-r_{j})^{N_{q}^{p}-(N-1)} \sup_{0 < \delta < 2(r'_{j}-r_{j})} \delta^{-1} \int\limits_{A_{j} \backslash (A_{j})_{\delta}} (|\nabla^{k}u_{n}| + |\nabla^{k}u|^{p}) \, dx \\ & + C \sum_{i=1}^{k} (r'_{j}-r_{j})^{-pi+N_{q}^{p}-(N-1)} \sup_{0 < \delta < 2(r'_{j}-r_{j})} \delta^{-1} \int\limits_{A_{j} \backslash (A_{j})_{\delta}} (|\nabla^{k-i}(u_{n}-u)|^{p}) \, dx. \end{split}$$

Since  $A_j \setminus (A_j)_{\delta} = B(x_0, r'_j) \setminus B(x_0, r'_j - \delta) \cup B(x_0, r_j + \delta) \setminus B(x_0, r_j)$ , using (23) we deduce that the last sum may be estimated from above by

$$\begin{split} &C(r'_j-r_j)^{N^{\underline{p}}_{\overline{q}}-(N-1)} \Biggl( M \phi_{n,j}(r_j) + M \phi_{n,j}(r'_j)) + \sum_{i=1}^k \frac{M \phi_{n,j}(r_j) + M \phi_{n,j}(r'_j)}{a_n (r'_j-r_j)^{pi}} \Biggr) \\ & \leq C(r'_i-r_j)^{N^{\underline{p}}_{\overline{q}}-(N-1)} \lambda \to 0, \end{split}$$

and this concludes the proof.

Proof of Lemma 3.4 and Lemma 3.5. As in Lemma 3.6 in [12], without loss of generality we may assume that f is p-coercive, i.e.  $\gamma > 0$  in (7). Appealing to Proposition 3.1, there exists a «minimizing sequence»  $\{u_n\}$  of smooth functions such that

$$u_n \rightharpoonup u$$
 in  $W^{k,p}(\Omega; \mathbb{R}^d)$ 

and

$$F(u_n,\cdot) \stackrel{*}{\rightharpoonup} \mathcal{R}(u,\cdot)$$
 in the sense of measures.

Let  $r_0$  be a radius which satisfies the properties described in Lemma 3.6 in this paper. Then for  $j=1,2,\ldots$ , there exist integers  $n_j\to\infty$ , radii  $r_j\nearrow r_0$ ,  $r_j'\searrow r_0$  and functions  $v_j\in W^{k,q}_{\mathrm{loc}}(\Omega;\mathbb{R}^d)$  such that  $v_j=u_{n_j}$  on  $\Omega\setminus (B(x,r_j')\setminus B(x_0,r_j))$ ,  $v_j-u\in W^{k,p}_0(B(x_0,r_0);\mathbb{R}^d)$  and

(27) 
$$\int\limits_{B(x_0,r_j')\setminus B(x_0,r_j)} |\nabla^k v_j|^q dx \to 0.$$

We may also assume that  $\mathcal{R}(u, \partial B(x_0, r_0)) = 0$ ). The functions  $v_j$  are legitimate test function for  $m(u, B(x_0, r_0))$ , and thus, using (7) and (27),

$$m(u, B(x_0, r_0)) \le \inf_{j} F(v_j, B(x_0, r_0))$$
  
 $\le \limsup_{n} F(u_n, B(x_0, r_0))$   
 $< \mathcal{R}(u, \overline{B}(x_0, r_0)) = \mathcal{R}(u, B(x_0, r_0)).$ 

This proves Lemma 3.4. Now, given a function  $v \in W^{k,q}(B(x_0, r_0); \mathbb{R}^d)$  with  $u - v \in W_0^{k,p}(B(x_0, r_0); \mathbb{R}^d)$ , we set

$$w_j =: \begin{cases} v & \text{on } B(x_0, r_0), \\ v_j & \text{outside } B(x_0, r_0). \end{cases}$$

Choose  $\delta > 0$ . Since  $w_j \rightharpoonup w$  in  $W^{k,p}(B(x_0, r_0 + \delta) \setminus \overline{B}(x_0, r_0 - \delta))$ , we have

$$\mathcal{R}(w, \partial B(x_0, r_0)) \leq \liminf_{j} F(w_j, B(x_0, r_0 + \delta) \setminus \overline{B}(x_0, r_0 - \delta))$$

$$\leq \limsup_{n} F(u_n, B(x_0, r_0 + \delta) \setminus \overline{B}(x_0, r_0))$$

$$+ F(v, B(x_0, r_0) \setminus \overline{B}(x_0, r_0 - \delta))$$

$$\leq \mathcal{R}(u, \overline{B}(x_0, r_0 + \delta) \setminus B(x_0, r_0))$$

$$+ F(v, B(x_0, r_0) \setminus \overline{B}(x_0, r_0 - \delta)).$$

Letting  $\delta \to 0+$  we easily observe that  $\mathcal{R}(w,\partial B(x_0,r_0))=0$ , and thus Lemma 3.5 is proved.

Proof of Theorem 1.8. The first part of the statement when p > N-1 follows immediately from Theorem 1.7 with q = N.

If now  $p>\frac{N^2}{N+2}$ , we choose  $\varepsilon>0$  and consider a sequence  $u_n\in W^{2,N}(\Omega)$  such that  $u_n\rightharpoonup u$  in  $W^{2,p}(\Omega)$  and

(28) 
$$\lim_{n \to \infty} \int_{\Omega} |\det \nabla^2 u_n(x)| \, dx < \mathcal{F}_H(u, \Omega, (W^{2,p}, w) + \varepsilon.$$

By Theorem 1.3 we have that  $\mathcal{H}u=\mathcal{H}_2^*u$ , and for all  $\varphi\in C_c^\infty(\Omega)$  and by (28)

$$\begin{aligned} |\langle \mathcal{H}u, \varphi \rangle| &= \left| \lim_{n \to \infty} \int_{\Omega} \varphi(x) \det \nabla^{2} u_{n}(x) \, dx \right| \\ &\leq \|\varphi\|_{L^{\infty}} (\mathcal{F}_{H}(u, \Omega, (W^{2,p}, w) + \varepsilon). \end{aligned}$$

Letting  $\varepsilon \to 0$  we obtain the assertion.

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#### Abstract

A weak formulation of the determinant of the matrix of second order derivatives is introduced and several of its properties are explored in analogy with the theory developed for the weak Jacobian.

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