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Partial Area.

PART III: Symmetrization and the Isoperimetric and Least Area Problems. (**)

13. – Let n = p + 1, m = p; in the notation of the previous parts q = 1 and the p-dimensional horizontal, and one-dimensional vertical, projections of a point $x \in [n]$ will again by y, z. The terms length and graph will be used for dimensions < p, usually for the dimension p = 1, while area and hypersurface are reserved for the dimension p = m, and volume and solid for p + 1 = n. When the dimension k is kept arbitrary, we shall substitute on occasion the neutral terms k-measure and k-variety. We note the following corollary of (9.1) of Part II:

(13.1) A closed generalized solid is always singular.

We term adjoint L^- of a generalized variety L, the generalized variety derived by reversing the orientation, i.e. defined by $L^-(f) = L(f^-)$, where $f^-(x, J) = f(x, -J)$.

Given a closed generalized (k-1)-variety Γ , we define a generalized k-variety L, termed cone of Γ with vertex x_0 , or simply cone of Γ , as follows: we associate to any k-integrand f the (k-1)-integrand

$$g(x, J) = \int_{0}^{1} f(x_0 + t (x - x_0), (x - x_0) \times J) t^{k-1} dt,$$

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^(**) Cf. Part. I: Riv. Mat. Univ. Parma 10 (1959), 103-113; Part. II: Contours on hypersurfaces, Riv. Mat. Univ. Parma 10 (1959), 171-182.

where $x \in [n]$, $J \in [n]^{k-1}$, and we define L by writing $L(f) = \Gamma(g)$. A simple calculation with corresponding exterior differential forms shows that we have f = Dg whenever f is exact, and hence that the cone of Γ is bounded by Γ .

Again, if Γ is any generalized (k-1)-variety situated in [p], we define a generalized k-variety L in [n], termed cylinder on Γ between the levels z_1 and z_2 , or simply cylinder on Γ , as follows: we associate to any k-integrand f in [n], the (k-1)-integrand g in [p] obtained by writing, for $g \in [p]$ and $g \in [p]^{k-1}$,

$$g(y, J_p) = \int_{z_1}^{z_1} f[(y, z), \zeta \times J_p] dz$$

where ζ is the vertical unit vector; and we define L by writing $L(f) = \Gamma(g)$. We shall only be concerned with the case in which Γ is bounded by a generalized (k-2)-variety Γ^* and a simple calculation then shows that L is bounded by the sum of the corresponding cylinder on Γ^* and two horizontal generalized (k-1)-varieties consisting of the translate of Γ in the hyperplane $z=z_1$ and that of its adjoint in the hyperplane $z=z_2$.

We term *minimal* generalized k-variety in a given class, one of smallest k-measure in that class. The minimum is attained if the class is closed and not empty, provided that the k-measures are not increased by restricting the varieties to be situated in some fixed ball. In particular a minimal generalized k-variety with given boundary, or bounded by a given closed (k-1)-variety, exists.

14. – We come to a lemma which will be the main tool of this part. Let Q_0 be in [n] a horizontal strip of height h_0 and let Q be any horizontal substrip $z_1 \leqslant z \leqslant z_2$ whose height z_2-z_1 we denote by h. Let L and \sum denote respectively a closed generalized hypersurface situated in Q_0 and a minimal generalized solid bounded by L, let L_Q , \sum_Q be their intersections with Q and let V, V_Q , A, A_Q denote the volumes of \sum , \sum_Q and the areas of L, L_Q . We denote further by s(z), or simply by s, the length of the slice $s_z L$, and by $\sigma(z)$, or simply by σ , the area of a minimal generalized hypersurface with the same boundary as L truncated below the level z.

(14.1) For almost any z, the slice $s_z \sum$ is a minimal generalized hypersurface of area $\sigma(z)$ bounded by $s_z L$ and we have

(i)
$$V \leqslant K h_0 A$$
, (ii) $V_Q = \int_{z_1}^{z_2} \sigma \, \mathrm{d}z$, (iii) $A \geqslant \int_{z_1}^{z_4} \sqrt{s^2 \, \mathrm{d}z^2 + \mathrm{d}\sigma^2}$,

where this last integral is in the sense of Burkill and where K denotes a certain constant factor depending only on n.

Proof. We first deal with (iii). We denote for $z=z_1$, by L_1 the (or a), minimal generalized hypersurface whose area was defined to be $\sigma(z_1)$, and we observe that the corresponding class for $z=z_2$ for which the minimum of the area was defined to be $\sigma(z_2)$ includes the generalized hypersurface L_1+PL_Q , where PL_Q is the horizontal projection of L_Q . Hence $\sigma(z_2) \leqslant \sigma(z_1) + A(PL_Q)$, and by combining this with the inequality derived by symmetry

$$A(P\ L_{\it q}) \geqslant \left|\ \sigma(z_{\scriptscriptstyle 2}) - \sigma(z_{\scriptscriptstyle 1})\ \right|$$
 .

Further, by (10.2) of Part II,

$$a(L_q) \gg \int_{z_1}^{z_2} s \, \mathrm{d}z$$
.

Moreover, since $|J| \ge |j| \cdot \cos \alpha + |J_p| \cdot \sin \alpha$ for all α , we evidently have $A(L_q) \ge a(L_q) \cdot \cos \alpha + A(P|L_q) \cdot \sin \alpha$, and by choice of α ,

$$A_{q} = A(L_{o}) \gg \{ a(L_{o})^{2} + A(P L_{o})^{2} \}^{1/2}.$$

Substituting from the previous inequalities this leads to

$$A_{\varrho}\geqslant \left\{\,(\int\limits_{z_{1}}^{z_{1}}\!\!s\,\,\mathrm{d}z)^{2}\,+\big[\sigma(z_{2})-\sigma(z_{1})\big]^{2}\,\right\}^{1/2}$$

and since this inequality holds for every Q, we deduce (iii).

We next reduce the remaining assertions to (i) which we therefore assume while doing so. We consider in the first instance the substrip Q for almost any z_1 , in which case $s_z L$ may be taken to be, for $z=z_1$, a closed generalized graph Γ_1 such that L_1 is bounded by Γ_1 . We denote by \sum_1 the cylinder on L_1 between the levels z_1 and z_2 , and by \sum_2 a minimal generalized solid bounded by the closed generalized hypersurface consisting of the sum of the following three terms:

 $L_{\it q};~$ the adjoint of the cylinder on $\varGamma_{\rm 1};$ the translate in $z=z_{\rm 2}$ of the adjoint of $P\;L_{\it q}$.

For fixed z_1 , the area of each of these three terms tends to 0 with h, and therefore by (i) the volume of \sum_2 is $<\varepsilon h$ where $\varepsilon\to 0$ as $h\to 0$. Also by the p-dimensional analogue of (13.1), \sum_q and $\sum_1+\sum_2$ have the same boundary, so that, from the minimal property, V_q cannot exceed the sum of the volumes of \sum_1 and \sum_2 . Since V_q is by (10.3) the integral from z_1 to z_2 of the area of s z, it follows that for almost every z_1 , by dividing by h and making $h\to 0$, $\sigma(z_1)$

coincides with the area of $s_z \sum$ for $z = z_1$. Hence $\sigma(z)$ is the area of $s_z \sum$ for almost every z and this establishes (ii) for an arbitrary Q. It is clear also that $s_z \sum$ is, for almost every z, a minimal generalized hypersurface bounded by $s_z L$, since it is bounded by the latter and has the minimal area $\sigma(z)$.

It remains to establish (i), which we rename (i)_n where the suffix denotes the dimension, and we shall do this by induction, in conjunction with the following statement, to which we shall refer as $(iv)_n$:

Let Δ denote the part of [n] obtained by restricting certain horizontal coordinates y_k to inequalities $a_k \leqslant y_k \leqslant a_k + h_0$ and let L be a closed generalized hypersurface of area A situated in Δ . Then, for some subdivision of the z-axis into intervals δ_r of length h_0 , there exists for each ν a closed generalized surface L_r , situated in the part Δ_r of Δ for which $z \in \delta_r$, with the following properties:

- (a) $L_r = 0$ except for a finite number of values of r;
- (b) The sum of the areas of the L_{ν} does not exceed a constant multiple of A,
- (e) The sum of the L_{r} may be written in the form $L+L^{*}$, where L^{*} is singular.
- 15. We proceed with our proof. From $(iv)_n$, by an easy induction combined with suitable rotations of axes, we deduce that with the hypotheses of (14.1) there exists a finite sum of closed generalized hypersurfaces L', where this sum differs from L only by a singular generalized hypersurface, such that:

Each L' is situated in a cube of side h_0 .

The sum of the areas of the L' does not exceed some constant multiple of A.

But this in turn implies (i)_n since we construct a generalized solid of volume $\leq K h_0 A$ bounded by L, simply by adding together cones on the L' with appropriate vertices.

Thus $(iv)_n$ implies $(i)_n$.

We verify next that $(i)_{n-1}$ implies $(iv)_n$ The statement of $(i)_{n-1}$ will be in terms of lengths and graphs instead of areas and hypersurfaces, since the dimension is lowered.

To this effect, with the hypotheses of $(iv)_n$, let s(t), $0 \le t \le h_0$, be the sum of the lengths of the slices $s_z L$ at the levels $z = t + vh_0$ for $v = 0, \pm 1, \ldots$

We note that this sum has only a finite number of non-vanishing terms, since L has to be situated in some ball of [n]. By (10.2)

$$A \geqslant \int_{0}^{h_0} s(t) dt$$

and therefore there exists a value of t for which $s(t) \leq A/h_0$. Such values of t occupy positive measure, and we choose one for which the numbers $z_r = t + vh$ $(v = 0, \pm 1, ...)$ are never among the sparse levels of the formula (10.1) of Part II.

We denote by δ_r the interval $z_{r-1} \leqslant z \leqslant z_r$, so that Δ_r is the corresponding part of Δ , and by Γ_r , Γ_r^- the slice $s_z L$ and its adjoint, when $z = z_r$. By (i)_{n-1} there exists a generalized hyperusrface L_r , bounded by Γ_r , whose area does not exceed a constant multiple of the product of h_0 and the length of Γ_r . We denote by L_r^- the adjoint of L_r , bounded by Γ_r^- , and we write L' (dropping the suffix) for the sum of

$$L_{\nu-1}; L_{\nu}^{-};$$
 the intersection of L with Δ_{ν} .

Evidently L' is a closed generalized surface situated in Δ_{ν} and the sum of the areas of the L' (for varying ν) is $\leq K h_0 s(t) \leq K A$. Further the sum of the L' consists, by definition, of L together with the sum of singular generalized surfaces $L_{\nu} + L_{\nu}^{-}$. This establishes (iv)_n as a consequence of (i)_{n-1}.

To complete the induction it now only remains to verify (i)_n in the case n = 1. This is easily done with the appropriate definitions (¹) of k-variety, etc., when k = 0, so that the proof of (14.1) is now complete.

16. – We now consider briefly the isoperimetric property of the n-dimensional ball. We denote by Θ the volume of the unit ball in [n] and by θ that of the unit ball in [m]. We write H for the class of generalized hypersurfaces which possess Lipschitzian tracks.

⁽¹⁾ A k-integrand, for k=0, is a function f(x, j) where j takes only the two values ± 1 , so that there is no longer any homogeneity in j. From well-known theorem of Banach it is easy to obtain the general form of a k-variety when k=0. In particular we find that a closed k-variety for k=0 is a finite sum $\sum a_{\nu} \{f(x_{\nu}, 1) + f(x'_{\nu}, -1)\}$, where the a_{ν} are ≥ 0 and the x_{ν} , x'_{ν} are points.

(16.1) Let A be the area of a closed generalized hypersurface $L \in H$ and let V be the volume of a minimal generalized solid bounded by L. Then

$$\left\{ \frac{A}{n\Theta} \right\}^n \geqslant \left\{ \frac{V}{\Theta} \right\}^{n-1}.$$

We prove this by induction, the case n=1 being easily verified. With the notation of (14.1) the inductive hypothesis ensures that, for almost every level z,

$$\{s/(m\theta)\}^m \gg \{\sigma/\theta\}^{m-1}$$
.

Writing $\sigma = \theta u^m$, it follows that $s \ge m \theta u^{m-1}$ so that (ii) and (iii) of (14.1) yield

$$V = \theta \cdot \int u^m \, \mathrm{d}z, \qquad A \geqslant m \theta \cdot \int u^{m-1} \, \sqrt{\mathrm{d}z^2 + \mathrm{d}u^2}.$$

Here the two right-hand members are, however, the volume and area of the solid and the hypersurface derived from the curve u = u(z) by revolution about the axis of z in n-space. The corresponding minimum problem being well known, we deduce the validity of our assertion for n, and so the truth of our theorem. The argument used is the well-known symmetrization process of Schwarz.

17. – Finally we come to our application to the least area problem. Let L be a generalized hypersurface in H with the boundary $\Gamma_1 + \Gamma_2$ where Γ_1 and Γ_2 are separated by a strip $z_1 < z < z_2 (= z_1 + h)$, that is to say Γ_1 is situated in the half-space $z < z_1$ and Γ_2 in the half-space $z > z_2$. We denote by A_1 and A_2 the least areas of two generalized hypersurfaces, bounded respectively by Γ_1 and Γ_2 ; and we write $A^*(A_1, A_2, h)$, or simply A^* , for the least area of a hypersurface of revolution, whose boundary is the sum of those of two m-dimensional balls of areas A_1 , A_2 at a distance h apart. The determination of A^* in terms of A_1 , A_2 , h is an elementary variational problem, and in particular so is that of formulating the conditions under which $A^* = A_1 + A_2$. We observe that the function A^* , as an immediate consequence of its definition as a minimum, is subject to an inequality of the form

$$A*(A_1,\ A_2,\ h) \leqslant A*(B_1,\ B_2,\ h)\ + \mid A_1 - B_1 \mid \ + \mid A_2 - B_2 \mid .$$

We shall prove that

(17.1) The area of L is at least A^* .

In particular if $A^* = A_1 + A_2$ we necessarily have a similar degeneracy in the least area problem for the boundary $\Gamma_1 + \Gamma_2$.

Proof of (17.1). Let Q be the strip $z_1 \leqslant z \leqslant z_2$ and let A_Q be the area of the intersection of L with Q. We shall apply (14.1) to the closed generalized hypersurface obtained by adding to L a minimal hypersurface bounded by Γ_1^- and a minimal hypersurface bounded by Γ_2^- , where Γ_1^- and Γ_2^- are the adjoints of Γ_1 and Γ_2 . We find that

$$A_{\it q} \geqslant \int\limits_{z_1}^{z_2} \sqrt{s^2 \, \mathrm{d}z^2 + \mathrm{d}\sigma^2}$$

and we again substitute $\sigma = \theta u^m$, so that, by the isoperimetric inequality, $s \ge m \theta u^{m-1}$ and therefore

$$A_q\geqslant m heta \cdot \int\limits_{z_1}^{z_2} u^{m-1}\,\sqrt{\mathrm{d}z^2+\,\mathrm{d}u^2}.$$

It follows that $A_q \geqslant A^*(B_1, B_2, h)$, where B_1 , B_2 are the values of θu^m for $z = z_1$ and for $z = z_2$, i.e. the corresponding values of $\sigma(z_1)$, $\sigma(z_2)$.

Now if A_{-} and A_{+} are the areas of the intersection of L with the half spaces $z < z_1$ and $z > z_2$ we evidently have

$$B_1 + A_- \geqslant A_1$$
 and $A_1 + A_- \geqslant B_1$,

i.e. $A_-\geqslant |A_1-B_1|$. Similarly $A_+\geqslant |A_2-B_2|$. Since the area of L is $A_-+A_0+A_+$, we find that it is

$$\geqslant A*(B_1,\ B_2,\ h)\ + \left|\ A_1 - B_1\ \right|\ + \left|\ A_2 - B_2\ \right| \geqslant A*(A_1,\ A_2,\ h)\ ,$$

which completes the proof.

References for Part III.

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