

M. FERNÁNDEZ and B. R. MOREIRAS (*)

Symmetry properties of the covariant derivative of the fundamental 4-form of a quaternionic manifold (**)

1 - Introduction

The group $Sp(n) \cdot Sp(1)$ is the structure group of a quaternionic manifold. On such a manifold M there is a fundamental (globally defined) 4-form Ω [4]. If Ω is parallel with respect to the Levi-Civita connection, then M is said to be a quaternionic Kähler manifold. In this case the holonomy group of M is a subgroup of $Sp(n) \cdot Sp(1)$ (see [1], [2]_{2,3}, [3], [6]).

In this paper we give some theorems, concerning some symmetric properties of the covariant derivative $\nabla\Omega$ of the fundamental 4-form Ω on M (Theorems 4.1, 4.2, 4.3).

2 - Preliminaries

Let (M, g) be a C^∞ $4n$ -dimensional Riemannian manifold. (M, g) is said to be a quaternionic manifold if the structural group $O(4n)$ of the frame bundle of M can be reduced to $Sp(n) \cdot Sp(1)$ or, equivalently, if there exists a 3-dimensional vector bundle V consisting of tensors of type $(1, 1)$ over M satisfying the condition that each point $p \in M$ has a neighborhood \mathcal{U} on which there is a local basis $\{I, J, K\}$ of V such that

$$(2.1) \quad \begin{aligned} I^2 = J^2 = K^2 = -1 \\ IJ = -JI = K \quad KI = -IK = J \quad JK = -KJ = I \end{aligned}$$

(*) Indirizzo: Departamento de Geometria y Topología, Facultad de Matemáticas, Univ. de Santiago, Santiago de Compostela, Spain and Univ. Pais Vasco, Bilbao, Spain.

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where 1 denotes the identity tensor field of type (1,1) on M

$$(2.2) \quad g(IX, IY) = g(JX, JY) = g(KX, KY) = g(X, Y)$$

for any vector fields X, Y on \mathcal{U} .

Since g is Hermitian with respect to each almost complex structures I, J and K , we can consider their Kähler local 2-forms F_I, F_J and F_K . Then,

$$\Omega = F_I \wedge F_I + F_J \wedge F_J + F_K \wedge F_K$$

is a globally defined 4-form on M (originally defined by Kraines [4]), which is called the fundamental form of the quaternionic manifold M . One easily verifies

$$(2.3) \quad \begin{aligned} & \Omega(X, Y, Z, U) \\ &= 2 \underset{yzu}{\mathfrak{S}} \{g(IX, Y)g(IZ, U) + g(JX, Y)g(JZ, U) + g(KX, Y)g(KZ, U)\} \end{aligned}$$

for any vector fields X, Y, Z, U on \mathcal{U} and where \mathfrak{S} denotes the cyclic sum. The quaternionic manifold is said to be Kählerian if Ω is parallel with respect to the Levi-Civita connection of g .

3 - Properties of the fundamental 4-form

In this section we study the properties of the fundamental 4-form Ω of a quaternionic manifold (M, g) with respect to the almost complex structures I, J and K .

Let us recall that the Kähler (local) 2-forms F_I, F_J and F_K satisfy

$$(3.1) \quad F_I(IX, IY) = F_I(X, Y) \quad F_J(JX, JY) = F_J(X, Y) \quad F_K(KX, KY) = F_K(X, Y)$$

$$(3.2) \quad F_I(X, IX) = F_J(X, JX) = F_K(X, KX) = \|X\|^2$$

for X, Y vector fields on \mathcal{U} .

A similar condition to (3.1) for Ω is given in the following

Proposition 3.1. *For any vector fields X, Y, Z, U on \mathcal{U} we have*

$$(3.3) \quad \begin{aligned} \Omega(IX, IY, IZ, IU) &= \Omega(JX, JY, JZ, JU) \\ &= \Omega(KX, KY, KZ, KU) = \Omega(X, Y, Z, U). \end{aligned}$$

Proof. From (2.1), (2.2) and (2.3) one follows that

$$\begin{aligned} & \Omega(IX, IY, IZ, IU) \\ &= 2 \underset{YZU}{\mathfrak{S}} \{g(X, IY)g(Z, IU) + g(JX, Y)g(JZ, U) + g(KX, Y)g(KZ, U)\} \\ &= 2 \underset{YZU}{\mathfrak{S}} \{g(IX, Y)g(IZ, U) + g(JX, Y)g(JZ, U) + g(KX, Y)g(KZ, U)\} \\ &= \Omega(X, Y, Z, U). \end{aligned}$$

This proves the first equality of (3.3). The remainder identities are proved in a similar way.

The analogous condition to (3.2) for Ω is given in the following

Proposition 3.2. *For any vector field X on \mathcal{U} we have*

$$(3.4) \quad \Omega(X, IX, JX, KX) = 6 \|X\|^4.$$

Proof. Direct computations from (2.3).

Finally, we also have

Proposition 3.3. *For any vector fields X, Y, Z, U on \mathcal{U} we have*

$$(3.5) \quad \underset{YZU}{\mathfrak{S}} \{\Omega(X, IY, JZ, KU) + \Omega(X, IY, JU, KZ)\} = 12 \underset{YZU}{\mathfrak{S}} g(X, Y)g(Z, U).$$

Proof. From (3.4), by polarization, we have

$$(3.6) \quad \begin{aligned} & \Omega(X + Y, IX + IY, JX + JY, KX + KY) \\ &= 6 \|X\|^4 + 6 \|Y\|^4 + 12 \{\|X\|^2 \|Y\|^2 + 2g(X, Y)^2 + 2g(X, Y) [\|X\|^2 + \|Y\|^2]\}. \end{aligned}$$

Using (3.3), (3.6) can be written as follows

$$\begin{aligned} & 2\Omega(X, IX, JX, KY) + 2\Omega(X, IY, JY, KY) \\ &+ \Omega(X, IX, JY, KY) + \Omega(X, KX, IY, JY) + \Omega(X, JX, KY, IY) \\ &= 6 \{\|X\|^2 \|Y\|^2 + 2g(X, Y)^2 + 2g(X, Y) [\|X\|^2 + \|Y\|^2]\}. \end{aligned}$$

If we replace Y and Z in this identity by $Y + Z$ and $Z + U$ we obtain (3.5).

4 - The covariant derivative of the fundamental 4-form

In this section we obtain several symmetry properties for the covariant derivative $\nabla\Omega$ of the fundamental 4-form Ω of the quaternionic manifold (M, g) , ∇ being the Levi-Civita connection of (M, g) .

It is well known that the covariant derivative ∇F_I of the Kähler 2-form F_I satisfies

$$(4.1) \quad \nabla_W(F_I)(X, Y) = -\nabla_W(F_I)(IX, IY)$$

for any vector fields X, Y, W on \mathcal{U} . Analogous equations hold when I is replaced by J or by K .

Furthermore, one easily verifies

$$(4.2) \quad \begin{aligned} \nabla_W(F_I)(JX, Y) &= \nabla_W(F_K)(X, Y) + \nabla_W(F_J)(X, IY) = \nabla_W(F_K)(IX, IY) - \nabla_W(F_J)(IX, Y) \\ \nabla_W(F_J)(IX, Y) + \nabla_W(F_J)(X, IY) &= \nabla_W(F_K)(IX, IY) - \nabla_W(F_K)(X, Y) \\ \nabla_W(F_I)(JX, Y) + \nabla_W(F_I)(X, JY) &= \nabla_W(F_K)(IX, IY) + \nabla_W(F_K)(X, Y) \\ \nabla_W(F_I)(JX, Y) - \nabla_W(F_I)(X, JY) &= \nabla_W(F_J)(X, IY) - \nabla_W(F_J)(IX, Y) \end{aligned}$$

$$(4.3) \quad \begin{aligned} \nabla_W(\Omega)(X, Y, Z, U) &= 2 \sum_{yzu} \{g(\nabla_W(I)X, Y)g(IZ, U) + g(\nabla_W(I)Z, U)g(IX, Y) \\ &+ g(\nabla_W(J)X, Y)g(JZ, U) + g(\nabla_W(J)Z, U)g(JX, Y) + g(\nabla_W(K)X, Y)g(KZ, U) \\ &+ g(\nabla_W(K)Z, U)g(KX, Y)\} = 2 \sum_{ijk} (\nabla_W(F_i) \wedge F_j)(X, Y, Z, U) \end{aligned}$$

for any vector fields W, X, Y, Z, U on \mathcal{U} .

Theorem 4.1. *The covariant derivative $\nabla\Omega$ of the fundamental 4-form Ω of (M, g) satisfies*

$$(4.4) \quad \nabla_W(\Omega)(X, IX, JX, KX) = 0$$

for all W, X vector fields on \mathcal{U} .

Proof. From (4.3) one follows that

$$\begin{aligned} \nabla_W(\Omega)(X, IX, JX, KX) &= 2\|X\|^2 \{g(\nabla_W(I)X, IX) + g(\nabla_W(I)JX, KX) + g(\nabla_W(J)X, JX) \\ &+ g(\nabla_W(J)KX, IX) + g(\nabla_W(K)X, KX) + g(\nabla_W(K)IX, JX)\}. \end{aligned}$$

From (4.1) and (4.2) each summand in this identity is zero which proves (4.4).

Proposition 4.1. *For any vector fields W, X, Y on \mathcal{M} we have*

$$(i) \quad \nabla_W(\Omega)(X, IX, JY, KY) + \nabla_W(\Omega)(JX, KX, Y, IY) = 0$$

$$(ii) \quad \nabla_W(\Omega)(X, IX, JX, KY) + \nabla_W(\Omega)(X, IX, JY, KX) \\ + \nabla_W(\Omega)(X, IY, JX, KX) + \nabla_W(\Omega)(Y, IX, JX, KX) = 0.$$

Proof. From (2.1), (2.2), (4.1) and (4.3) we get

$$(4.5) \quad \nabla_W(\Omega)(X, IX, JY, KY) = 2\{g(X, Y)[g(\nabla_W(J)X, JY) - g(\nabla_W(J)IX, KY) \\ + g(\nabla_W(K)X, KY) + g(\nabla_W(K)IX, JY)] + g(IX, Y)[g(\nabla_W(J)X, KY) \\ + g(\nabla_W(J)IX, JY) - g(\nabla_W(K)X, JY) + g(\nabla_W(K)IX, KY)]\}.$$

If we replace X and Y in (4.5) by JX and JY and add the result with (4.5) we obtain (i). In order to prove (ii) we first replace Y in (i) by $X + Y$. Then, from (4.4) and (i) we deduce (ii).

Proposition 4.2. *For any vector fields W, X, Y, Z, U on \mathcal{M} we have*

$$\nabla_W(\Omega)(X, Y, Z, U) + \nabla_W(\Omega)(IX, IY, IZ, IU) \\ = 2 \sum_{yzu} \{[g(\nabla_W(J)X, Y) - g(\nabla_W(J)IX, IY)]g(JZ, U) \\ + [g(\nabla_W(J)Z, U) - g(\nabla_W(J)IZ, IU)]g(JX, Y) \\ + [g(\nabla_W(K)X, Y) - g(\nabla_W(K)IX, IY)]g(KZ, U) \\ + [g(\nabla_W(K)Z, U) - g(\nabla_W(K)IZ, IU)]g(KX, Y)\}.$$

Similar results can be obtained by cyclic permutations of I, J, K .

Proof. From (2.1), (2.2), (4.1) and (4.3) we have

$$(4.6) \quad \nabla_W(\Omega)(IX, IY, IZ, IU) = -2 \sum_{yzu} \{g(\nabla_W(I)X, Y)g(IZ, U) \\ + g(\nabla_W(I)Z, U)g(IX, Y) + g(\nabla_W(J)IX, IY)g(JZ, U) \\ + g(\nabla_W(J)IZ, IU)g(JX, Y) + g(\nabla_W(K)IX, IY)g(KZ, U) \\ + g(\nabla_W(K)IZ, IU)g(KX, Y)\}.$$

Now, from (4.3) and (4.6) one gets the formula.

Corollary. For W, X, Y, Z, U vector fields on \mathcal{U} we have

$$\begin{aligned} & \nabla_W(\Omega)(X, Y, Z, U) - \nabla_W(\Omega)(IX, IY, IZ, IU) \\ &= 2 \underset{YZU}{\cong} \{2[g(\nabla_W(I)X, Y)g(IZ, U) + g(\nabla_W(I)Z, U)g(IX, Y)] \\ &+ [g(\nabla_W(J)X, Y) + g(\nabla_W(J)IX, IY)]g(JZ, U) \\ &+ [g(\nabla_W(J)Z, U) + g(\nabla_W(J)IZ, IU)]g(JX, Y) \\ &+ [g(\nabla_W(K)X, Y) + g(\nabla_W(K)IX, IY)]g(KZ, U) \\ &+ [g(\nabla_W(K)Z, U) + g(\nabla_W(K)IZ, IU)]g(KX, Y)\}. \end{aligned}$$

Similar results can be obtained by cyclic permutations of I, J, K .

Proof. It suffices to subtract (4.6) from (4.3).

Theorem 4.2. For any vector fields W, X, Y, Z, V on \mathcal{U} we have

$$(4.7) \quad \begin{aligned} & \nabla_W(\Omega)(X, Y, Z, U) + \nabla_W(\Omega)(IX, IY, IZ, IU) \\ &+ \nabla_W(\Omega)(JX, JY, JZ, JU) + \nabla_W(\Omega)(KX, KY, KZ, KU) = 0. \end{aligned}$$

Proof. From (2.1), (2.2), (4.1) and (4.3) we obtain

$$(4.8) \quad \begin{aligned} & \nabla_W(\Omega)(JX, JY, JZ, JU) = -2 \underset{YZU}{\cong} \{g(\nabla_W(I)JX, JY)g(IZ, U) \\ &+ g(\nabla_W(J)Z, U)g(JX, Y) + g(\nabla_W(I)JZ, JU)g(IX, Y) + g(\nabla_W(J)X, Y)g(JZ, U) \\ &- g(\nabla_W(K)IX, IY)g(KZ, U) - g(\nabla_W(K)IZ, IU)g(KX, Y)\}, \end{aligned}$$

$$(4.9) \quad \begin{aligned} & \nabla_W(\Omega)(KX, KY, KZ, KU) = 2 \underset{YZU}{\cong} \{g(\nabla_W(I)JX, JY)g(IZ, U) \\ &+ g(\nabla_W(I)JZ, JU)g(IX, Y) + g(\nabla_W(J)IX, IY)g(JZ, U) \\ &+ g(\nabla_W(J)IZ, IU)g(JX, Y) - g(\nabla_W(K)X, Y)g(KZ, U) \\ &- g(\nabla_W(K)Z, U)g(KX, Y)\}. \end{aligned}$$

Summing up term to term (4.3), (4.6), (4.8) and (4.9) we obtain (4.7).

Theorem 4.3. For W, X, Y, Z, U vector fields on \mathcal{Z} we have

$$\begin{aligned}
 (4.10) \quad & \nabla_W(\Omega)(X, Y, Z, U) + \nabla_W(\Omega)(KX, KY, KZ, KU) \\
 &= \nabla_W(\Omega)(X, Y, KZ, KU) + \nabla_W(\Omega)(X, KY, Z, KU) + \nabla_W(\Omega)(KX, KY, Z, U) \\
 &+ \nabla_W(\Omega)(KX, Y, KZ, U) + \nabla_W(\Omega)(X, KY, KZ, U) + \nabla_W(\Omega)(KX, Y, Z, KU).
 \end{aligned}$$

The result is still true replacing K by I or by J .

Proof. We put

$$(4.11) \quad I' = aI + bJ \quad J' = -bI + aJ \quad K' = K$$

where a, b are real numbers such that $a^2 + b^2 = 1$. Then $\{I', J', K'\}$ is also a basis of V on \mathcal{Z} , and the fundamental 4-form Ω' corresponding to $\{I', J', K'\}$ is equal to Ω . Now, we replace I, J, K in (4.7) by I', J', K' . Then, using (4.11) we obtain

$$\begin{aligned}
 (4.12) \quad 0 = & \nabla_W(\Omega)(X, Y, Z, U) + \nabla_W(\Omega)(KX, KY, KZ, KU) \\
 &+ (a^4 + b^4) \{ \nabla_W(\Omega)(IX, IY, IZ, IU) + \nabla_W(\Omega)(JX, JY, JZ, JU) \} \\
 &+ (a^3b - ab^3) \{ \nabla_W(\Omega)(IX, IY, IZ, JU) + \nabla_W(\Omega)(IX, IY, IZ, IU) \\
 &+ \nabla_W(\Omega)(IX, JY, IZ, IU) + \nabla_W(\Omega)(JX, IY, IZ, IU) \\
 &- \nabla_W(\Omega)(JX, JY, JZ, IU) - \nabla_W(\Omega)(JX, JY, IZ, JU) \\
 &- \nabla_W(\Omega)(JX, IY, JZ, JU) - \nabla_W(\Omega)(IX, JY, JZ, JU) \} \\
 &+ 2a^2b^2 \{ \nabla_W(\Omega)(IX, IY, JZ, JU) + \nabla_W(\Omega)(IX, JY, IZ, JU) \\
 &+ \nabla_W(\Omega)(IX, JY, JZ, IU) + \nabla_W(\Omega)(JX, IY, IZ, JU) \\
 &+ \nabla_W(\Omega)(JX, IY, JZ, IU) + \nabla_W(\Omega)(JX, JY, IZ, IU) \}.
 \end{aligned}$$

Furthermore, since $a^4 + b^4 = 1 - 2a^2b^2$, using (4.7) we get

$$\begin{aligned}
 (4.13) \quad & \nabla_W(\Omega)(IX, IY, IZ, IU) + \nabla_W(\Omega)(JX, JY, JZ, JU) \\
 &= \nabla_W(\Omega)(IX, IY, JZ, JU) + \nabla_W(\Omega)(IX, JY, IZ, JU) + \nabla_W(\Omega)(IX, JY, JZ, IU) \\
 &+ \nabla_W(\Omega)(JX, IY, IZ, JU) + \nabla_W(\Omega)(JX, IY, JZ, IU) + \nabla_W(\Omega)(JX, JY, IZ, IU).
 \end{aligned}$$

Replacing X, Y, Z, U in (4.13) by IX, IY, IZ and IU we deduce (4.10).

It is well known that any 2-dimensional almost Hermitian manifold is Kählerian. Actually, we have the following

Proposition 4.3. *Let M be a 4-dimensional quaternionic manifold. Then M is a Kähler quaternionic manifold.*

Proof. Let $\{X, IX, JX, KX\}$ an arbitrary local frame field. Using Theorem 4.1. we get $\nabla_Y(\Omega)(X, IX, JX, KX) = 0$ for any vector field Y on \mathcal{U} . Hence the proposition follows.

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Résumé

Nous étudions les propriétés de symétrie de la dérivée covariante $\nabla\Omega$ de la 4-forme fondamentale Ω d'une variété Riemannienne dont le groupe structurel c'est $Sp(n) \cdot Sp(1)$.

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